

The Borsuk–Ulam Theorem

Anthony Carbery

University of Edinburgh &
Maxwell Institute for Mathematical Sciences

May 2010

Outline

- 1 Brouwer fixed point theorem
- 2 Borsuk–Ulam theorem
 - Introduction
 - Case $n = 2$
 - Dimensional reduction
 - Case $n = 3$
- 3 An application
- 4 A question

Brouwer fixed point theorem

The **Brouwer fixed point theorem** states that every continuous map $f : \mathbb{D}^n \rightarrow \mathbb{D}^n$ has a fixed point.

When $n = 1$ this is a trivial consequence of the intermediate value theorem.

In higher dimensions, if not, then for some f and all $x \in \mathbb{D}^n$, $f(x) \neq x$.

So the map $\tilde{f} : \mathbb{D}^n \rightarrow \mathbb{S}^{n-1}$ obtained by sending x to the unique point on \mathbb{S}^{n-1} on the line segment starting at $f(x)$ and passing through x is continuous, and when restricted to the boundary $\partial\mathbb{D}^n = \mathbb{S}^{n-1}$ is the identity.

So to prove the Brouwer fixed point theorem it suffices to show there is **no** map $g : \mathbb{D}^n \rightarrow \mathbb{S}^{n-1}$ which restricted to the boundary \mathbb{S}^{n-1} is the identity. (In fact, this is an equivalent formulation.)

Proof of Brouwer's theorem

It is enough, by a standard approximation argument, to prove that there is no **smooth** (C^1) map $g : \mathbb{D}^n \rightarrow \mathbb{S}^{n-1}$ which restricted to the boundary \mathbb{S}^{n-1} is the identity.

Consider, for Dg the derivative matrix of g ,

$$\int_{\mathbb{D}^n} \det Dg.$$

This is zero as Dg has less than full rank at each $x \in \mathbb{D}^n$.

So

$$0 = \int_{\mathbb{D}^n} \det Dg = \int_{\mathbb{D}^n} dg_1 \wedge dg_2 \wedge \cdots \wedge dg_n,$$

which, by Stokes' theorem equals

$$\int_{\mathbb{S}^{n-1}} g_1 dg_2 \wedge \cdots \wedge dg_n.$$

This quantity depends only the behaviour of g_1 on \mathbb{S}^{n-1} , and, by symmetry, likewise depends only on the restrictions of g_2, \dots, g_n to \mathbb{S}^{n-1} .

But on \mathbb{S}^{n-1} , g is the identity I , so that reversing the argument, this quantity also equals

$$\int_{\mathbb{D}^n} \det DI = |\mathbb{D}^n|.$$

This argument is essentially due to E. Lima. Is there a similarly simple proof of the Borsuk–Ulam theorem via Stokes' theorem?

Borsuk–Ulam theorem

The Borsuk–Ulam theorem states that for every continuous map $f : \mathbb{S}^n \rightarrow \mathbb{R}^n$ there is some x with $f(x) = f(-x)$. When $n = 1$ this is a trivial consequence of the intermediate value theorem.

In higher dimensions, it again suffices to prove it for smooth f .

So assume f is smooth and $f(x) \neq f(-x)$ for all x . Then

$$\tilde{f}(x) := \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$$

is a smooth map $\tilde{f} : \mathbb{S}^n \rightarrow \mathbb{S}^{n-1}$ such that $\tilde{f}(-x) = -\tilde{f}(x)$ for all x , i.e. \tilde{f} is *odd*, *antipodal* or *equivariant* with respect to the map $x \mapsto -x$.

So it's ETS there is no equivariant smooth map $h : \mathbb{S}^n \rightarrow \mathbb{S}^{n-1}$, or, equivalently, **there is no smooth map $g : \mathbb{D}^n \rightarrow \mathbb{S}^{n-1}$ which is equivariant on the boundary.**

Equivalent to Borsuk–Ulam theorem; BU generalises Brouwer fixed point theorem (since the identity map is equivariant).

WTS there does not exist a smooth $g : \mathbb{D}^2 \rightarrow \mathbb{S}^1$ such that $g(-x) = -g(x)$ for $x \in \mathbb{S}^1$. If there did exist such a g , consider

$$\int_{\mathbb{D}^2} \det Dg = \int_{\mathbb{D}^2} dg_1 \wedge dg_2.$$

This is zero as Dg has less than full rank at each x , and it equals, by Stokes' theorem,

$$\int_{\mathbb{S}^1} g_1 dg_2 = - \int_{\mathbb{S}^1} g_2 dg_1.$$

So it's enough to show that

$$\int_0^1 (g_1(t)g_2'(t) - g_2(t)g_1'(t))dt \neq 0$$

for $g = (g_1, g_2) : \mathbb{R}/\mathbb{Z} \rightarrow \mathbb{S}^1$ satisfying $g(t + 1/2) = -g(t)$ for all $0 \leq t \leq 1$.

ETS

$$\int_0^1 (g_1(t)g_2'(t) - g_2(t)g_1'(t))dt \neq 0$$

for $g = (g_1, g_2) : \mathbb{R}/\mathbb{Z} \rightarrow \mathbb{S}^1$ satisfying $g(t + 1/2) = -g(t)$ for all $0 \leq t \leq 1$.

Clearly

$$(g_1(t)g_2'(t) - g_2(t)g_1'(t))dt$$

represents the element of net arclength for the curve $(g_1(t), g_2(t))$ measured in the anticlockwise direction. (Indeed, $|g| = 1$ implies $\langle g, g' \rangle = \frac{1}{2} \frac{d}{dt} |g|^2 = 0$, so that $\det(g, g') = \pm |g| |g'| = \pm |g'|$, with the plus sign occurring when g is moving anticlockwise.) By equivariance, $(g_1(1/2), g_2(1/2)) = -(g_1(0), g_2(0))$, and

$$\int_0^1 g_1(t)g_2'(t)dt = 2 \int_0^{1/2} g_1(t)g_2'(t)dt.$$

In passing from $(g_1(0), g_2(0))$ to $(g_1(1/2), g_2(1/2))$ the total net arclength traversed is clearly an odd multiple of π , and so we're done.

Theorem (Shchepin)

Suppose $n \geq 4$ and there exists a smooth equivariant map $f : \mathbb{S}^n \rightarrow \mathbb{S}^{n-1}$. Then there exists a smooth equivariant map $\tilde{f} : \mathbb{S}^{n-1} \rightarrow \mathbb{S}^{n-2}$.

Once this is proved, only the case $n = 3$ of the Borsuk–Ulam theorem remains outstanding.

Starting with f , we shall identify suitable equators $E_{n-1} \subseteq \mathbb{S}^n$ and $E_{n-2} \subseteq \mathbb{S}^{n-1}$, and build a smooth equivariant map $\tilde{f} : E_{n-1} \rightarrow E_{n-2}$.

We first need to know that there is some pair of antipodal points $\{\pm A\}$ in the target \mathbb{S}^{n-1} whose preimages under f are covered by finitely many diffeomorphic copies of $(-1, 1)$. This is intuitively clear by dimension counting (WMA f is onto!) but for rigour we can appeal to Sard's theorem.

For $x \in f^{-1}(A)$ and $y \in f^{-1}(-A) = -f^{-1}(A)$ with $y \neq -x$, consider the unique geodesic great circle joining x to y . The family of such is clearly indexed by the **two-parameter** family of points of

$$f^{-1}(A) \times f^{-1}(-A) \setminus \{(x, -x) : f(x) = A\}.$$

Their union is therefore a manifold in \mathbb{S}^n of dimension at most three.

Since $n \geq 4$ there must be points $\pm B \in \mathbb{S}^n$ outside this union (and necessarily outside $f^{-1}(A) \cup f^{-1}(-A)$). Such a point has the property that no geodesic great circle passing through it meets points of both $f^{-1}(A)$ and $f^{-1}(-A)$ other than possibly at antipodes. In particular, no meridian joining $\pm B$ meets both $f^{-1}(A)$ and $f^{-1}(-A)$.

We now identify E_{n-2} as the equator of \mathbb{S}^{n-1} whose equatorial plane is perpendicular to the axis joining A to $-A$; and we identify E_{n-1} as the equator of \mathbb{S}^n whose equatorial plane is perpendicular to the axis joining B to $-B$. We assume for simplicity that B is the north pole $(0, 0, \dots, 0, 1)$.

Lemma (Lemma 1)

Suppose $B = (0, 0, \dots, 0, 1) \in \mathbb{S}^n$ and that $X \subseteq \mathbb{S}^n$ is a closed subset such that no meridian joining $\pm B$ meets both X and $-X$. Let \mathbb{S}_\pm^n denote the open upper and lower hemispheres respectively. Then there is an equivariant diffeomorphism $\psi : \mathbb{S}^n \rightarrow \mathbb{S}^n$ such that

$$X \subseteq \psi(\mathbb{S}_+^n).$$

Remark 1. It is clear that we may assume that ψ fixes meridians and acts as the identity on small neighbourhoods of $\pm B$.

Remark 2. It is also clear from the proof that we can find a smooth family of diffeomorphisms ψ_t such that ψ_0 is the identity and $\psi_1 = \psi$.

We shall need this later.

Lemma

Suppose $B = (0, 0, \dots, 0, 1) \in \mathbb{S}^n$ and that $X \subseteq \mathbb{S}^n$ is a closed subset such that no meridian joining $\pm B$ meets both X and $-X$. Let \mathbb{S}_{\pm}^n denote the open upper and lower hemispheres respectively. Then there is an equivariant diffeomorphism $\psi : \mathbb{S}^n \rightarrow \mathbb{S}^n$ such that

$$X \subseteq \psi(\mathbb{S}_+^n).$$

Continuing with the proof of the theorem, we apply the lemma with $X = f^{-1}(A)$. Let ϕ be restriction of ψ to $E = E_{n-1}$. Consider the restriction \hat{f} of f to $\phi(E)$: it has the property that $\hat{f}(\phi(E))$ does not contain $\pm A$. Let r be the standard retraction of $\mathbb{S}^{n-1} \setminus \{\pm A\}$ onto its equator E_{n-2} ; finally let

$$\tilde{f} = r \circ \hat{f} \circ \phi,$$

which is clearly smooth and equivariant.

Proof of Lemma

See the pictures on the blackboard!

The Sard argument

WTS there is some pair of antipodal points $\{\pm A\}$ in the target \mathbb{S}^{n-1} whose preimages under f are at most “one-dimensional”, i.e. covered by finitely many diffeomorphic copies of $(-1, 1)$.

Sard's theorem tells us that the image under f of the set $\{x \in \mathbb{S}^n : \text{rank } Df(x) < n - 1\}$ is of Lebesgue measure zero: so there are plenty of points $A \in \mathbb{S}^{n-1}$ at all of whose preimages x – if there are any at all – $Df(x)$ has full rank $n - 1$. By the implicit function theorem, for each such x there is a neighbourhood $B(x, r)$ such that $B(x, r) \cap f^{-1}(A)$ is diffeomorphic to the interval $(-1, 1)$. The whole of the compact set $f^{-1}(A)$ is covered by such balls, from which we can extract a finite subcover: so indeed $f^{-1}(A)$ is covered by finitely many diffeomorphic copies of $(-1, 1)$.

Proposition (Shchepin)

Suppose that $f : \mathbb{S}^3 \rightarrow \mathbb{S}^2$ is a smooth equivariant map. Then there exists a smooth $f^\dagger : \mathbb{D}^3 \rightarrow \mathbb{S}^2$ which is equivariant on $\partial\mathbb{D}^3 = \mathbb{S}^2$, and moreover maps \mathbb{S}^2_\pm to itself.

Discussion: By identifying the closed upper hemisphere of \mathbb{S}^3 with the closed disc \mathbb{D}^3 we obtain a smooth map

$$\widehat{f} : \mathbb{D}^3 \rightarrow \mathbb{S}^2$$

which is equivariant on $\partial\mathbb{D}^3 = \mathbb{S}^2$.

Then the restriction of \widehat{f} to $\partial\mathbb{D}^3 = \mathbb{S}^2$ gives a smooth equivariant map $g : \mathbb{S}^2 \rightarrow \mathbb{S}^2$. If we could take g to be the identity, we would be finished – the argument given for the Brouwer fixed point theorem showed that no such \widehat{f} exists.

We cannot hope for this, but we can hope to “improve” the properties of g so that a similar argument will work. What we need more precisely is that g maps \mathbb{S}^2_\pm to itself.

Proposition implies BU

Suppose there existed a smooth map $f^\dagger : \mathbb{D}^3 \rightarrow \mathbb{S}^2 \subseteq \mathbb{R}^3$ which was equivariant on $\partial\mathbb{D}^3 = \mathbb{S}^2$, and mapped \mathbb{S}^2_\pm to itself.

Let C be the cylinder $\mathbb{D}^2 \times [-1, 1]$ in \mathbb{R}^3 with top and bottom faces D_\pm and curved vertical boundary $V = \mathbb{S}^1 \times [-1, 1]$. Let S_\pm be the upper and lower halves of $S = \partial C$. Let E be the equator of S .

Now C , with the all points on each vertical line of V identified, is diffeomorphic to \mathbb{D}^3 , and S is also diffeomorphic to \mathbb{S}^2 .

Lemma

There is no smooth map $f : C \rightarrow S$ which is equivariant on ∂C , which is constant on vertical lines in V and which maps D_\pm into S_\pm .

Proposition

There is no smooth map $f : C \rightarrow S$ which is equivariant on ∂C , which is constant on vertical lines in V and which maps D_{\pm} into S_{\pm} .

If such an f existed, then

$$\int_C \det Df = \int_C df_1 \wedge df_2 \wedge df_3$$

where Df is the derivative matrix of f . On the one hand this is zero as Df has less than full rank at almost every $x \in C$, and on the other hand it equals, by Stokes' theorem,

$$\int_{\partial C} f_3 df_1 \wedge df_2 = \int_V f_3 df_1 \wedge df_2 + 2 \int_{D_+} f_3 df_1 \wedge df_2$$

by equivariance.

$$0 = \int_V f_3 df_1 \wedge df_2 + 2 \int_{D_+} f_3 df_1 \wedge df_2$$

Now f maps V into E , so that $f_3 = 0$ on V , and the first term on the right vanishes.

As for the second term,

$$\int_{D_+} f_3 df_1 \wedge df_2 = \int_{D_+ \cap \{x : f_3(x)=1\}} f_3 df_1 \wedge df_2 + \int_{D_+ \cap \{x : f_3(x)<1\}} f_3 df_1 \wedge df_2.$$

The region of D_+ on which $f_3(x) < 1$ consists of patches on which $f_1^2(x) + f_2^2(x) = 1$, and so $2f_1 df_1 + 2f_2 df_2 = 0$. Taking exterior products with df_1 and df_2 tells us that on such patches we have

$f_1 df_1 \wedge df_2 = f_2 df_1 \wedge df_2 = 0$. Multiplying by f_1 and f_2 and adding we get that $h df_1 \wedge df_2 = 0$ for all h supported on a patch on which $f_3(x) < 1$. So for any h we have

$$\int_{D_+ \cap \{x : f_3(x)<1\}} h df_1 \wedge df_2 = 0.$$

Hence

$$\begin{aligned} \int_{D_+} f_3 \, df_1 \wedge df_2 &= \int_{D_+ \cap \{x : f_3(x)=1\}} df_1 \wedge df_2 \\ &= \int_{D_+ \cap \{x : f_3(x)=1\}} df_1 \wedge df_2 + \int_{D_+ \cap \{x : f_3(x)<1\}} df_1 \wedge df_2 \\ &= \int_{D_+} df_1 \wedge df_2. \end{aligned}$$

By Stokes' theorem once again we have

$$\int_{D_+} df_1 \wedge df_2 = \int_{\partial D_+} f_1 df_2 = - \int_{\partial D_+} f_2 df_1,$$

and, since f restricted to ∂D_+ is equivariant, this quantity is nonzero (and indeed is an odd multiple of π), by the remarks in the proof of the case $n = 2$ above.

So no such f exists and we are done.

Proof of Proposition

Proposition (Shchepin)

Suppose that $f : \mathbb{S}^3 \rightarrow \mathbb{S}^2$ is a smooth equivariant map. Then there exists a smooth $f^\dagger : \mathbb{D}^3 \rightarrow \mathbb{S}^2$ which is equivariant on $\partial\mathbb{D}^3 = \mathbb{S}^2$, and moreover maps \mathbb{S}^2_\pm to itself.

Recall that f induces first $\widehat{f} : \mathbb{D}^3 \rightarrow \mathbb{S}^2$ (identifying the upper closed hemisphere of \mathbb{S}^3 with \mathbb{D}^3), and then a smooth equivariant $g : \mathbb{S}^2 \rightarrow \mathbb{S}^2$ by restricting \widehat{f} to the boundary of \mathbb{D}^3 .

Lemma (Lemma 8)

If $g : \mathbb{S}^2 \rightarrow \mathbb{S}^2$ is a smooth equivariant map, then there exists a smooth equivariant $g^\dagger : \mathbb{S}^2 \rightarrow \mathbb{S}^2$ which preserves the upper and lower hemispheres of \mathbb{S}^2 .

We shall then extend g^\dagger to all of \mathbb{D}^3 , “interpolating” between g^\dagger on \mathbb{S}^2 and \widehat{f} on a shrunken \mathbb{D}^3 .

Proof of Lemma 8

(Equivariant $g : \mathbb{S}^2 \rightarrow \mathbb{S}^2 \implies$ hemisphere preserving g^\dagger .)

- Choose $\pm A$ in target \mathbb{S}^2 such that $g^{-1}(\pm A)$ are finite.
- Choose $\pm B$ (wlog N and S poles) in domain \mathbb{S}^2 s.t. meridional projections of $g^{-1}(\pm A)$ on standard equator E are distinct.
- Apply Lemma 3 with $X = g^{-1}(A)$: \exists equivariant diffeo $\psi : \mathbb{S}^2 \rightarrow \mathbb{S}^2$ s.t. $g^{-1}(A) \subseteq \psi(\mathbb{S}_+^2)$.
- So $g_* := g \circ \psi$ is a smooth equivariant selfmap of \mathbb{S}^2 ; $g_*^{-1}(A) \subseteq \mathbb{S}_+^2$.
- Let $\tilde{g} : E \rightarrow E$ be the meridional projection of $g_*(x)$ on E . (Well-defined since $g_*^{-1}(\pm A) \cap E = \emptyset$.) Then \tilde{g} smooth and equivariant.

We next extend \tilde{g} to a small strip around E :

Extend \tilde{g} to a small strip around E ; and then to all of \mathbb{S}^2 .

- For $x \in \mathbb{S}^2$ let $l(x) \in [-\pi/2, \pi/2]$ denote its latitude with respect to E .
- For $x \neq \pm B$, let \bar{x} denote its meridinal projection on E .
- For $0 < r < \pi/2$ let $E_r = \{x \in \mathbb{S}^2 : |l(x)| \leq r\}$.
- Consider only r so small that $E_r \cap g_*^{-1}(\pm A) = \emptyset$. Let $d = \text{dist}(\pm A, g_*(E))$.
- Since g_* is uniformly continuous, there is an $r > 0$ such that for $x \in E_r$ we have $d(g_*(x), g_*(\bar{x})) < d/10$.
- Now extend \tilde{g} to E_r by defining $\tilde{g}(x)$ to be the point with the same longitude (meridinal projection) as $\tilde{g}(\bar{x})$ and with latitude $\pi l(x)/2r$. This extension is still equivariant and smooth.
- Define $\tilde{g}(x) = A$ for $l(x) > r$ and $\tilde{g}(x) = -A$ for $l(x) < -r$. Then \tilde{g} is continuous, equivariant, preserves the upper and lower hemispheres and – except possibly on the sets $\{x : l(x) = \pm r\}$ – is smooth.

Thus \tilde{g} satisfies all the properties we needed for g^\dagger except for smoothness.

We shall need to sort this out and to also simultaneously establish an auxiliary property of \tilde{g} which we'll need for the interpolation step to work.

Claim: For all $x \in \mathbb{S}^2$, $\tilde{g}(x) \neq -g_*(x)$.

Claim: For all $x \in \mathbb{S}^2$, $\tilde{g}(x) \neq -g_*(x)$.

- Consider, for $x \in E_r$, the three points $g_*(x)$, $g_*(\bar{x})$ and $\tilde{g}(x)$.
- Now $g_*(\bar{x})$ and $\tilde{g}(x)$ are on the same meridian, and $g_*(\bar{x})$ is distant at least d from $\pm A$.
- On the other hand, $g_*(x)$ is at most $d/10$ from $g_*(\bar{x})$.
- Thus $g_*(x)$ is at least $9d/10$ from $\pm A$ and lives in a $d/10$ -neighbourhood of the common meridian containing $g_*(\bar{x})$ and $\tilde{g}(x)$.
- So for $x \in E_r$, $g_*(x)$ cannot equal $-\tilde{g}(x)$.
- For $l(x) > r$ we have $\tilde{g}(x) = A$ and $g_*(x) \neq -A$ because $g_*^{-1}(-A)$ is contained in the lower hemisphere.
- Similarly for $l(x) < -r$, $\tilde{g}(x) \neq -g_*(x)$. Thus for all $x \in \mathbb{S}^2$ we have $\tilde{g}(x) \neq -g_*(x)$.

Mollify \tilde{g} in small neighbourhoods of $\{x : l(x) = \pm r\}$ (and then renormalise to ensure that the target space remains \mathbb{S}^2 !) to obtain g^\dagger which is smooth, equivariant, preserves the upper and lower hemispheres and, being uniformly very close to \tilde{g} , is such that $g^\dagger(x) \neq -g_*(x)$ for all x .

Hence we also have, with ψ as above,

$$g^\dagger(x) \neq -(g \circ \psi)(x) \text{ for all } x.$$

Let ψ_t be a smooth family of diffeomorphisms interpolating between $\psi_0 = l$ and $\psi_1 = \psi$.

With this in hand, the proposition follows by defining, for $x \in \mathbb{S}^2$ and $0 \leq t \leq 1$, $\tilde{f} : \mathbb{D}^3 \rightarrow \mathbb{S}^2$ by

$$\tilde{f}(tx) = \frac{(3t-2)g^\dagger(x) + (3-3t)(g \circ \psi)(x)}{|(3t-2)g^\dagger(x) + (3-3t)(g \circ \psi)(x)|} \text{ when } 2/3 \leq t \leq 1,$$

$$\tilde{f}(tx) = g \circ \psi_{3t-1}(x) \text{ when } 1/3 \leq t \leq 2/3$$

and

$$\tilde{f}(tx) = \hat{f}(3tx) \text{ when } 0 \leq t \leq 1/3.$$

This makes sense because for $2/3 \leq t \leq 1$ we have $(3t-2)g^\dagger(x) + (3-3t)(g \circ \psi)(x) \neq 0$; then \tilde{f} has all the desired properties of f^\dagger (including continuity) except possibly for smoothness at $t = 1/3$ and $2/3$. To rectify this we mollify \tilde{f} in a small neighbourhood of $\{t = 1/3\}$ and $\{t = 2/3\}$ and renormalise once more to ensure that the target space is indeed still \mathbb{S}^2 . The resulting f^\dagger now has all the properties we need.

Borsuk–Ulam again

Theorem (Borsuk–Ulam)

If $F : \mathbb{S}^M \rightarrow \mathbb{R}^M$ is continuous, then there is some x with $F(x) = F(-x)$.

So if F is also odd, i.e. $F(-x) = -F(x)$ for all x , then there is some x with $F(x) = 0$.

Trivially the same applies to functions $F : \mathbb{S}^M \rightarrow \mathbb{R}^N$ with $M \geq N$ – just add extra zero components of F until there are M of them.

A typical application

Theorem (Ham Sandwich Theorem)

Suppose we have open sets U_1, \dots, U_n in \mathbb{R}^n . Then there exists a hyperplane bisecting each U_j .

If P is a hyperplane $\{x : a_0 + a_1x_1 + \dots + a_nx_n = 0\}$, let $P^+ = \{x : a_0 + a_1x_1 + \dots + a_nx_n > 0\}$ and similarly for P^- . Note that changing the signs of all the coefficients swaps P^\pm . We say P **bisects** U if $|U \cap P^+| = |U \cap P^-|$.

Every point $\mathbf{a} = (a_0, \dots, a_n) \in \mathbb{S}^n \subseteq \mathbb{R}^{n+1}$ corresponds to some hyperplane $P_{\mathbf{a}}$.

Then the map

$$\mathbf{a} \mapsto \left\{ \int_{U_j \cap P_{\mathbf{a}}^+} 1 - \int_{U_j \cap P_{\mathbf{a}}^-} 1 \right\}_{j=1}^n$$

is a continuous odd map from \mathbb{S}^n to \mathbb{R}^n and so there is an \mathbf{a} which maps to zero.

So, given n 1-separated unit balls B_1, \dots, B_n in \mathbb{R}^n , there is a degree 1 algebraic hypersurface (i.e. a hyperplane!) Z such that

$$\mathcal{H}_{n-1}(Z \cap B_j) \geq C_n.$$

Here, \mathcal{H}_{n-1} denotes $n - 1$ -dimensional surface area.

More generally, if we have *many more* balls than the dimension n , can we find an algebraic hypersurface Z – not of degree 1 but of *controlled degree* – such that

$$\mathcal{H}_{n-1}(Z \cap B) \geq C_n$$

for all B ?

Yes!

In fact, we have:

Proposition (Stone-Tukey, Gromov)

Suppose we have $N \gg n$ 1-separated unit balls B in \mathbb{R}^n . Then there exists an algebraic hypersurface Z such that

$$(i) \quad \deg Z \leq C_n N^{1/n}$$

and

$$(ii) \quad \mathcal{H}_{n-1}(Z \cap B) \geq C_n$$

for all B .

Proof of Proposition

Given 1-separated $\{x_1, \dots, x_N\} \subseteq \mathbb{R}^n$. Then there is a p with $\deg p \leq C_n N^{1/n}$ and zero set Z such that $\mathcal{H}^{n-1}(Z \cap B(x_j, 1)) \geq C_n$ for all j .

Consider the map

$$F : p \mapsto \left\{ \int_{\{p>0\} \cap B(x_j, 1)} 1 - \int_{\{p<0\} \cap B(x_j, 1)} 1 \right\}_j$$

defined on $X_{d,n} = \{ \text{polys of degree } \leq d \text{ in } n \text{ real variables} \}$.

Clearly F is continuous, homogeneous of degree 0 and odd.

So we can think of F as

$$F : \mathbb{S}^M \rightarrow \mathbb{R}^N$$

where \mathbb{S}^M – with $M + 1 = \binom{n+d}{n} \sim d^n$ – is the unit sphere of $X_{d,n}$.

So by Borsuk–Ulam, if $M \geq N$, then F vanishes at some p .

For such p (which we can choose with $\deg p \leq C_n N^{1/n}$) we have $\mathcal{H}^{n-1}(Z \cap B(x_j, 1)) \geq C_n$ for all j .

We've seen that given $N \gg n$ 1-separated unit balls B in \mathbb{R}^n , then there exists an algebraic hypersurface Z such that

$$(i) \quad \deg Z \leq C_n N^{1/n}$$

and

$$(ii) \quad \mathcal{H}_{n-1}(Z \cap B) \geq C_n$$

for all B .

What about a version of this “with multiplicities”?

That is, given 1-separated unit balls B_j in \mathbb{R}^n and given $M_j \geq 1$, can we find an algebraic hypersurface Z such that

$$(i) \quad \deg Z \leq C_n \left(\sum_j M_j^n \right)^{1/n}$$

and

$$(ii) \quad \mathcal{H}_{n-1}(Z \cap B_j) \geq C_n M_j$$

for all j ?

Proposition

Given 1-separated unit balls B_j in \mathbb{R}^n and given $M_j \geq 1$, we can find an algebraic hypersurface Z such that

$$(i) \quad \deg Z \leq C_n \left(\sum_j M_j^n \right)^{1/n}$$

and

$$(ii) \quad \mathcal{H}_{n-1}(Z \cap B_j) \geq C_n M_j$$

for all j

Proof.

Chop each B_j into M_j^n equal sub-balls and apply the same strategy: we obtain M_j^n contributions of $M_j^{-(n-1)}$ to $Z \cap B_j$ and the total number of constraints is $\sum_j M_j^n$. □

A Question

Let $S_e(Z)$ be the component of surface area of Z in the direction perpendicular to the unit vector e . Let $\{e_j(Q)\}$ be any approximate orthonormal basis and let $S_j(Q) = S_{e_j}(Z \cap Q)$.

By the G.M./A.M. inequality we have

$$\prod_{j=1}^n S_j(Q)^{1/n} \leq C_n \sum_{j=1}^n S_j(Q) \sim \mathcal{H}_{n-1}(Z \cap Q)$$

because the directions involved in the S_j are approximately orthonormal.

So a *harder* task is, given M , to find a polynomial p of degree at most $C_n (\sum_Q M(Q)^n)^{1/n}$, with zero set Z , such that

$$M(Q) \leq C_n \prod_{j=1}^n S_j(Q)^{1/n} \text{ for all } Q \in \text{supp } M.$$

Algebraic geometry and algebraic topology

Something close to this is indeed true and is a consequence of work of Guth on the multilinear Kakeya problem.

However, the argument currently relies upon the whole machinery of algebraic topology. Some of the tools needed:

- \mathbb{Z}_2 -cohomology
- Covering spaces
- Cup products
- Lusternik–Schnirelmann theory
- Commutative diagrams and long exact sequences

Is there an “elementary” proof of this result appealing directly to Borsuk–Ulam?