

# THE GEOMETRIC HOPF INVARIANT

Michael Crabb (Aberdeen)

Andrew Ranicki (Edinburgh)

- ▶ When is a  $k$ -stable map  $F : \Sigma^k X \rightarrow \Sigma^k Y$  homotopic to the  $k$ -fold suspension  $\Sigma^k F_0$  of an unstable map  $F_0 : X \rightarrow Y$ ?
- ▶ The geometric Hopf invariant is the stable  $\mathbb{Z}_2$ -equivariant map

$$h_\infty(F) = (F \wedge F)\Delta_X - \Delta_Y F : X \rightarrow Y \wedge Y$$

with  $\Delta_X(x) = (x, x)$ ,  $T(x) = x$ ,  $T(y_1, y_2) = (y_2, y_1)$ .

- ▶ *The stable  $\mathbb{Z}_2$ -equivariant homotopy class of  $h_\infty(F)$  is the primary obstruction to the  $k$ -fold desuspension of  $F$ .*
- ▶ Need non-simply-connected  $h_\infty(F)$  for surgery theory.

## The Hopf invariant $H$ , the suspension map $E$ and the *EHP* sequence

- ▶ (Hopf 1931) Isomorphism  $H : \pi_3(S^2) \cong \mathbb{Z}$  via linking numbers of  $S^1 \sqcup S^1 \hookrightarrow S^3$ .
- ▶ (Freudenthal 1937) Suspension map for pointed space  $X$

$$E : \pi_n(X) \rightarrow \pi_{n+1}(\Sigma X); (f : S^n \rightarrow X) \mapsto (\Sigma f : S^{n+1} \rightarrow \Sigma X).$$

( $E$  for *Einhangung*). If  $X$  is  $(m-1)$ -connected then  $E$  is an isomorphism for  $n \leq 2m-2$  and surjective for  $n = 2m-1$ .

- ▶ (G.W.Whitehead 1950) *EHP* exact sequence

$$\cdots \rightarrow \pi_n(X) \xrightarrow{E} \pi_{n+1}(\Sigma X) \xrightarrow{H} \pi_n(X \wedge X) \xrightarrow{P} \pi_{n-1}(X) \rightarrow \cdots$$

for any  $(m-1)$ -connected space  $X$ , with  $n \leq 3m-2$ .

For  $X = S^m$ ,  $n = 2m$   $H$  is a Hopf invariant map

$$H : \pi_{2m+1}(S^{m+1}) \rightarrow \pi_{2m}(S^m \wedge S^m) = \mathbb{Z}.$$

**$k$ -fold desuspension = compression into  $X \subset \Omega^k \Sigma^k X$**

- ▶ For any connected pointed space  $X$  and  $k \geq 1$  the  $k$ -fold suspension map is induced by the inclusion  $X \subset \Omega^k \Sigma^k X$

$$E^k : \pi_n(X) \xrightarrow{E} \pi_{n+1}(\Sigma X) \xrightarrow{E} \pi_{n+2}(\Sigma^2 X) \\ \xrightarrow{E} \dots \xrightarrow{E} \pi_{n+k}(\Sigma^k X) = \pi_n(\Omega^k \Sigma^k X) .$$

- ▶ A map  $F : \Sigma^k Y \rightarrow \Sigma^k X$  is homotopic to  $\Sigma^k F_0$  for  $F_0 : Y \rightarrow X$  if and only if the adjoint map

$$\text{adj}(F) : Y \rightarrow \Omega^k \Sigma^k X ; y \mapsto (s \mapsto F(s, y))$$

can be factored up to homotopy through  $X \subset \Omega^k \Sigma^k X$ .

## The combinatorial models for $\Omega^k \Sigma^k X$

- Theorem (James 1955) For any pointed space  $X$  map

$$X \times X \rightarrow \Omega \Sigma X .$$

For connected  $X$  a stable homotopy decomposition

$$\Omega \Sigma X \simeq_s \bigvee_{j=1}^{\infty} (\bigwedge_j X) .$$

- (Dyer-Lashof 1962) For any pointed space  $X$  and  $k \geq 1$  map

$$S^{k-1} \times_{\mathbb{Z}_2} (X \times X) \rightarrow \Omega^k \Sigma^k X .$$

(Snaith 1974) Stable homotopy decomposition

$$\Omega^{\infty} \Sigma^{\infty} X \simeq_s \bigvee_{j=1}^{\infty} (E\Sigma_j)^+ \wedge_{\Sigma_j} (\bigwedge_j X) \quad (k = \infty)$$

for connected  $X$ . Also  $\Omega^k \Sigma^k X$  with  $1 \leq k < \infty$  (May 1975).  
Also for disconnected  $X = Y^+$  (Barratt, Quillen, 1970's).

## The stable $\mathbb{Z}_2$ -equivariant homotopy groups

- ▶ Given pointed spaces  $X, Y$  let  $[X, Y]$  be the set of homotopy classes of maps  $X \rightarrow Y$ . The stable homotopy group is

$$\{X; Y\} = \varinjlim_V [V^\infty \wedge X, V^\infty \wedge Y]$$

with  $V$  running over finite-dimensional real vector spaces, and  $V^\infty = V \cup \{\infty\}$  the one-point compactification.

- ▶ Given pointed  $\mathbb{Z}_2$ -spaces  $X, Y$  let  $[X, Y]_{\mathbb{Z}_2}$  be the set of homotopy classes of maps  $X \rightarrow Y$ . The stable  $\mathbb{Z}_2$ -equivariant homotopy group is

$$\{X; Y\}_{\mathbb{Z}_2} = \varinjlim_U \varinjlim_V [U^\infty \wedge LV^\infty \wedge X, U^\infty \wedge LV^\infty \wedge Y]_{\mathbb{Z}_2}$$

where  $LV = V$  with the  $\mathbb{Z}_2$ -action

$$T : LV \rightarrow LV ; v \mapsto -v .$$

## The quadratic construction

- ▶ The quadratic construction on a pointed space  $X$  is defined for any inner product space  $V$  to be the pointed space

$$Q_V(X) = S(LV)^+ \wedge_{\mathbb{Z}_2} (X \wedge X)$$

with  $S(LV) = \{v \in LV \mid \|v\| = 1\}$ ,  $S(LV)^+ = S(LV) \cup \{*\}$ ,

$$T : X \wedge X \rightarrow X \wedge X ; (x, y) \mapsto (y, x) .$$

The projection  $\tilde{Q}_V(X) = S(LV)^+ \wedge (X \wedge X) \rightarrow Q_V(X)$  is a double cover away from the base point. For  $1 \leq k \leq \infty$  write

$$Q_k(X) = Q_{\mathbb{R}^k}(X) , \quad \tilde{Q}_k(X) = \tilde{Q}_{\mathbb{R}^k}(X) .$$

In particular,  $Q_\infty(X) = \varinjlim_k Q_k(X) = Q_{\mathbb{R}^\infty}(X)$ .

- ▶ Example  $Q_0(X) = \{\text{pt.}\}$ ,  $Q_1(X) = X \wedge X$ .
- ▶ Example  $Q_k(S^0) = (S^{k-1})^+ / \mathbb{Z}_2 = (\mathbb{R}P^{k-1})^+$ .

## The relative difference

- ▶ For any inner product space  $V$  there is a cofibration

$$S^0 = 0^\infty \rightarrow V^\infty \rightarrow V^\infty/0^\infty = \Sigma S(V)^+ \rightarrow S^1 \rightarrow \dots$$

with a homeomorphism

$$\Sigma S(V)^+ \rightarrow V^\infty/0^\infty ; (t, u) \mapsto [t, u] = \frac{tu}{1-t} .$$

- ▶ Given maps  $p, q : V^\infty \wedge X \rightarrow Y$  such that

$$p(0, x) = q(0, x) \in Y \quad (x \in X)$$

define the relative difference map

$$\begin{aligned} \delta(p, q) : \Sigma S(V)^+ \wedge X &\rightarrow Y ; \\ (t, u, x) &\mapsto \begin{cases} p([1-2t, u], x) & \text{if } 0 \leq t \leq 1/2 \\ q([2t-1, u], x) & \text{if } 1/2 \leq t \leq 1 . \end{cases} \end{aligned}$$

The homotopy class of  $\delta(p, q)$  is the obstruction to the existence of a rel  $0^\infty \wedge X$  homotopy  $p \simeq q : V^\infty \wedge X \rightarrow Y$ .

**$\mathbb{Z}_2$ -equivariant stable homotopy theory**  
**= fixed-point + fixed-point-free**

- ▶ Theorem For any pointed spaces  $X, Y$  there is an exact sequence of abelian groups

$$0 \rightarrow \{X; Q_\infty(Y)\} \xrightarrow{1+T} \{X; Y \wedge Y\}_{\mathbb{Z}_2} \xrightarrow{\rho} \{X; Y\} \rightarrow 0$$

with

$$\{X; Q_\infty(Y)\} = \varinjlim_V [\Sigma S(LV)^+ \wedge X, LV^\infty \wedge Y \wedge Y]_{\mathbb{Z}_2} \text{ (S-duality).}$$

- ▶  $\rho$  is given by the  $\mathbb{Z}_2$ -fixed points, with nonadditive section

$$\sigma : \{X; Y\} \rightarrow \{X; Y \wedge Y\}_{\mathbb{Z}_2}; F \mapsto (F \wedge F)\Delta_X.$$

- ▶ The injection  $1 + T$  is induced by projection  $(S^\infty)^+ \rightarrow 0^\infty$

$$1 + T : \{X; Q_\infty(Y)\} = \{X; \tilde{Q}_\infty(Y)\}_{\mathbb{Z}_2} \rightarrow \{X; Y \wedge Y\}_{\mathbb{Z}_2},$$

with nonadditive projection

$$h : \{X; Y \wedge Y\}_{\mathbb{Z}_2} \rightarrow \{X; Q_\infty(Y)\}; G \mapsto \delta(\sigma\rho(G), G).$$



## The stable geometric Hopf invariant $h_\infty(F)$

- The stable geometric Hopf invariant of a stable map  
 $F : \Sigma^k X \rightarrow \Sigma^k Y$  is

$$\begin{aligned} h_\infty(F) &= (F \wedge F)\Delta_X - \Delta_Y F = \delta(\Delta_Y F, (F \wedge F)\Delta_X) \\ &\in \ker(\rho : \{X; Y \wedge Y\}_{\mathbb{Z}_2} \rightarrow \{X; Y\}) \\ &= \text{im}(1 + T : \{X; Q_\infty(Y)\} \hookrightarrow \{X; Y \wedge Y\}_{\mathbb{Z}_2}) . \end{aligned}$$

- Proposition (i) The function

$$h_\infty : \{X; Y\} \rightarrow \{X; Q_\infty(Y)\} ; F \mapsto h_\infty(F)$$

is nonadditive, being quadratic in nature:

$$h_\infty(F + G) = h_\infty(F) + h_\infty(G) + (F \wedge G)\Delta_X$$

(ii) If  $F \in \text{im}([X, Y] \rightarrow \{X; Y\})$  then  $h_\infty(F) = 0$ .

- Example If  $X = Y = S^0$ ,  $k = 1$ ,  $d \in \mathbb{Z}$ ,  
 $F = d : \Sigma X = S^1 \rightarrow \Sigma Y = S^1$  then

$$h_\infty(F) = d(d - 1)/2 \in \{0^\infty; Q_\infty(0^\infty)\} = \mathbb{Z}$$

## Double points

- ▶ The ordered double point set of a map  $f : M \rightarrow N$  is the free  $\mathbb{Z}_2$ -set

$$\tilde{D}_2(f) = \{(x, y) \mid x \neq y \in M, f(x) = f(y) = N\}$$

with  $\mathbb{Z}_2$  acting by  $T(x, y) = (y, x)$ .

- ▶ The unordered double point set is

$$D_2(f) = \tilde{D}_2(f)/\mathbb{Z}_2 .$$

- ▶  $f$  is an embedding if and only if  $D_2(f) = \emptyset$ .
- ▶ *The geometric Hopf invariant is the primary homotopy theoretic method of capturing  $D_2(f)$ .*

## Immersion of spaces

- Definition A map  $f : M \rightarrow N$  is an immersion of spaces if there exists an open embedding of the type

$$g = (e, f) : V \times M \hookrightarrow V \times N ; (v, x) \mapsto (e(v, x), f(x))$$

with  $V$  finite dimensional, for some map  $e : V \times M \rightarrow V$ , so that there is defined a commutative diagram

$$\begin{array}{ccc} V \times M & \xrightarrow{g} & V \times N \\ \downarrow & & \downarrow \\ M & \xrightarrow{f} & N \end{array}$$

The Umkehr map of  $g$  is the stable map

$$F : (V \times N)^\infty = V^\infty \wedge N^\infty \rightarrow (V \times M)^\infty = V^\infty \wedge M^\infty ;$$

$$(w, y) \mapsto \begin{cases} (v, x) & \text{if } (w, y) = g(v, x) \\ \infty & \text{if } (w, y) \notin \text{im}(g) . \end{cases}$$

- Example A codimension 0 immersion of manifolds.

## Capturing double points with homotopy theory

- ▶ Let  $f : M \rightarrow N$  be an immersion of spaces, with embedding  $g = (e, f) : V \times M \hookrightarrow V \times N$ . The  $\mathbb{Z}_2$ -equivariant product embedding

$$g \times g : V \times V \times M \times M \hookrightarrow V \times V \times N \times N$$

restricts to a  $\mathbb{Z}_2$ -equivariant embedding

$$g \times g| : V \times V \times D_2(f) \hookrightarrow V \times V \times N$$

with  $\mathbb{Z}_2$ -equivariant Umkehr map

$$G : V^\infty \wedge V^\infty \wedge N^\infty \rightarrow V^\infty \wedge V^\infty \wedge D_2(f)^+ .$$

- ▶ Define also the  $\mathbb{Z}_2$ -equivariant map

$$H : D_2(f)^+ \rightarrow \tilde{Q}_V(M^\infty) = S(LV)^+ \wedge (M^\infty \wedge M^\infty) ;$$

$$(x, y) \mapsto \left( \frac{e(0, x) - e(0, y)}{\|e(0, x) - e(0, y)\|}, x, y \right) .$$

## Double points of immersions of manifolds

- ▶ The double point set  $D_2(f)$  of a generic immersion  $f : M^m \looparrowright N^n$  with normal bundle  $\nu_f : M \rightarrow BO(n - m)$  is a  $(2m - n)$ -dimensional manifold. For  $k \geq 2m - n + 1$  there exists a map  $e : M \rightarrow \mathbb{R}^k$  such that

$$g = (e, f) : M \hookrightarrow \mathbb{R}^k \times N ; x \mapsto (e(x), f(x))$$

is an embedding with normal bundle

$$\nu_g = \nu_f \oplus \epsilon^k : M \rightarrow BO(n - m + k) .$$

- ▶ By the tubular neighbourhood theorem can approximate the product immersion  $1 \times f : \mathbb{R}^k \times M \looparrowright \mathbb{R}^k \times N$  by an embedding

$$\bar{g} = (\bar{e}, \bar{f}) : \mathbb{R}^k \times E(\nu_f) \hookrightarrow \mathbb{R}^k \times N$$

extending  $g$ , with  $\bar{f} : E(\nu_f) \looparrowright N$  a codimension 0 immersion.  $E(\nu_f)^\infty = T(\nu_f) = \text{Thom space}$ . Write Umkehr map of  $\bar{g}$  as

$$F : \Sigma^k N^\infty \rightarrow \Sigma^k T(\nu_f) .$$

## The Double Point Theorem

- Theorem If  $f : M^m \looparrowright N^n$  is an immersion of manifolds with Umkehr map  $F : \Sigma^k N^\infty \rightarrow \Sigma^k T(\nu_f)$  ( $k$  large) then

$$h_\infty(F) = HG$$

$$\begin{aligned} &\in \ker(\rho : \{N^\infty; T(\nu_f) \wedge T(\nu_f)\}_{\mathbb{Z}_2} \rightarrow \{N^\infty; T(\nu_f)\}) \\ &= \text{im}(\{N^\infty; Q_\infty(T(\nu_f))\} \hookrightarrow \{N^\infty; T(\nu_f) \wedge T(\nu_f)\}_{\mathbb{Z}_2}) \end{aligned}$$

is a factorization of  $h_\infty(F)$  through  $D_2(f)^+$ , with

$$N^\infty \xrightarrow{G} T(\nu_f \times \nu_f|_{D_2(f)}) \xrightarrow{H} T(\nu_f \times \nu_f) = T(\nu_f) \wedge T(\nu_f) .$$

- If  $f : M \looparrowright N$  is regular homotopic to an embedding  $f_0 : M \hookrightarrow N$  with Umkehr map  $F_0 : N^\infty \rightarrow T(\nu_f)$  then  $F$  is stably homotopic to  $F_0$ , and  $h_\infty(F)$  is stably null-homotopic.

## The difference of diagonals

- ▶ For any space  $X$  the diagonal map

$$\Delta_X : X \rightarrow X \wedge X ; x \mapsto (x, x)$$

is  $\mathbb{Z}_2$ -equivariant.

- ▶ For any f.d. inner product space  $V$  define  $\mathbb{Z}_2$ -equivariant homeomorphism

$$\kappa_V : LV^\infty \wedge V^\infty \rightarrow V^\infty \wedge V^\infty ; (x, y) \mapsto (x + y, -x + y) .$$

- ▶ Given a map  $F : V^\infty \wedge X \rightarrow V^\infty \wedge Y$  define the noncommutative square of  $\mathbb{Z}_2$ -equivariant maps

$$\begin{array}{ccc}
 LV^\infty \wedge V^\infty \wedge X & \xrightarrow{1 \wedge \Delta_X} & LV^\infty \wedge V^\infty \wedge X \wedge X \\
 \downarrow 1 \wedge F & (\kappa_V^{-1} \wedge 1)(F \wedge F)(\kappa_V \wedge 1) & \downarrow \\
 LV^\infty \wedge V^\infty \wedge Y & \xrightarrow{1 \wedge \Delta_Y} & LV^\infty \wedge V^\infty \wedge Y \wedge Y
 \end{array}$$

## The unstable geometric Hopf invariant $h_V(F)$

- Definition The unstable geometric Hopf invariant of a map  $F : V^\infty \wedge X \rightarrow V^\infty \wedge Y$  is the  $\mathbb{Z}_2$ -equivariant relative difference map

$$h_V(F) = \delta(p, q) : \Sigma S(LV)^+ \wedge V^\infty \wedge X \rightarrow LV^\infty \wedge V^\infty \wedge Y \wedge Y$$

of the  $\mathbb{Z}_2$ -equivariant maps

$$p = (1 \wedge \Delta_Y)F, \quad q = (\kappa_V^{-1} \wedge 1)(F \wedge F)(\kappa_V \wedge 1) : \\ LV^\infty \wedge V^\infty \wedge X \rightarrow LV^\infty \wedge V^\infty \wedge Y \wedge Y$$

with  $\Sigma S(LV)^+ = LV^\infty / 0^\infty = (LV \setminus \{0\})^\infty$ .

- The stable  $\mathbb{Z}_2$ -equivariant homotopy class of  $h_V(F)$  depends only on the homotopy class of  $F$ , defining a function

$$h_V : [V^\infty \wedge X, V^\infty \wedge Y] \rightarrow \\ \{\Sigma S(LV)^+ \wedge V^\infty \wedge X, LV^\infty \wedge V^\infty \wedge Y \wedge Y\}_{\mathbb{Z}_2} = \{X, Q_V(Y)\}$$



## Some properties of $h_V(F)$

- ▶ Composition and addition formulae

$$h_V(GF) = (G \wedge G)h_V(F) + h_V(G)F ,$$

$$h_V(F + F') = h_V(F) + h_V(F') + (F \wedge F')\Delta .$$

- ▶ If  $F \simeq 1_V \wedge F_0$  for some  $F_0 : X \rightarrow Y$  then

$$h_V(F) = 0 \in \{X, Q_V(Y)\} .$$

- ▶ The Double Point Theorem has unstable version, with  $h_V(F)$ .
- ▶ The original Hopf invariant of a map

$$F : S^{2m+1} = \Sigma(S^{2m}) \rightarrow S^{m+1} = \Sigma(S^m)$$

is

$$H(F) = h_{\mathbb{R}}(F) \in \{S^{2m}, Q_{\mathbb{R}}(S^m)\} = \{S^{2m}, S^{2m}\} = \mathbb{Z} .$$

## The universal example

- ▶ For any pointed space  $X$  evaluation defines a  $k$ -stable map

$$e : \Sigma^k(\Omega^k \Sigma^k X) \rightarrow \Sigma^k X ; (s, \omega) \mapsto \omega(s)$$

with  $\text{adj}(e) = 1 : \Omega^k \Sigma^k X \rightarrow \Omega^k \Sigma^k X$ . The unstable geometric Hopf invariant of  $e$  defines a stable map

$$h_{\mathbb{R}^k}(e) : \Omega^k \Sigma^k X \rightarrow Q_k(X) = (S^{k-1})^+ \wedge_{\mathbb{Z}_2} (X \wedge X)$$

which is a stable splitting of the Dyer-Lashof map.

- ▶ For any  $k$ -stable map  $F : \Sigma^k Y \rightarrow \Sigma^k X$  the stable homotopy class of the composite

$$h_{\mathbb{R}^k}(F) : Y \xrightarrow{\text{adj}(F)} \Omega^k \Sigma^k X \xrightarrow{h_{\mathbb{R}^k}(e)} Q_k(X)$$

is the primary obstruction to a  $k$ -fold desuspension of  $F$ , i.e. to the compression of  $\text{adj}(F)$  into  $X \subset \Omega^k \Sigma^k X$ .