

TD5

$\mathfrak{g}$  abelian     $\mathfrak{g}$  solvable     $\mathfrak{g}$  not semisimple. In particular  $\mathfrak{g} = \mathfrak{A}$  is not a simple Lie algebra by def.

ex 5.1:  $\mathfrak{r} \subset \mathfrak{g}$  semisimple.  $\mathfrak{a} \subset \mathfrak{g}$  abelian ideal.

$$\mathfrak{a} \subset \mathfrak{r} = \text{radical} = 0$$

$$\text{so } \mathfrak{a} = 0.$$

Conversely assume no nontrivial abelian ideal.

$$\mathfrak{r} \subset \mathfrak{g}$$

If  $\mathfrak{g}$  is not semisimple,  $0 \neq \mathfrak{r} \supset D\mathfrak{r} \supset D^2\mathfrak{r} \supset \dots \supset D^s\mathfrak{r} = 0$

$$D^{s-1}\mathfrak{r} \neq 0.$$

decreasing sequence of ideals of  $\mathfrak{g}$

$0 \neq D^{s-1}\mathfrak{r}$  abelian ideal of  $\mathfrak{g}$ .

$$\left[ \begin{array}{l} \mathfrak{a} \subset \mathfrak{g} \text{ ideal} \\ [\mathfrak{a}, \mathfrak{a}] \text{ ideal.} \\ \text{or } a, a' \in \mathfrak{a}, z \in \mathfrak{g} \\ [z, [a, a']] \\ = -[a, [z, a']] \\ = -[a', [z, a]] \\ \in \mathfrak{a}. \end{array} \right.$$

2.  $\Delta \subset \mathfrak{h}^*$  root system.  $\Delta$  generates  $\mathfrak{g}^*$ .

$$\text{let } h \in \mathfrak{h}, \alpha(h) = 0 \quad \forall \alpha \in \Delta.$$

$$* [h, \mathfrak{h}] = 0 \quad \text{since } \mathfrak{h} \text{ is commutative}$$

$$* x \in \mathfrak{g}_\alpha, \alpha \in \Delta, [h, x] = \alpha(h) \cdot x = 0.$$

$$\Rightarrow h \in Z(\mathfrak{g}) = 0. \therefore h = 0. \text{ so } \text{Vect}(\Delta) = \mathfrak{h}^*.$$

ex 5.2:

$$2. [\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] = \mathbb{C}h_\alpha, \quad h_\alpha \in \mathfrak{h}, \alpha(h_\alpha) \neq 0.$$

If  $0 \neq \mathfrak{a} \subset \mathfrak{g}$  abelian ideal.

$$\mathfrak{h} \oplus \bigoplus_{\alpha \in \Delta} \mathfrak{g}_\alpha$$

$\mathfrak{h} \xrightarrow{\text{ad}} \mathfrak{a}$  action.

$$\mathfrak{a} = (\mathfrak{a} \cap \mathfrak{h}) \oplus \bigoplus_{\alpha \in \Delta} (\mathfrak{a} \cap \mathfrak{g}_\alpha)$$

$$\left[ \begin{array}{l} \mathfrak{g} \cong V = \bigoplus_{i=1}^n V_i \\ W = \bigoplus W_i \\ W_i = W \cap V_i. \end{array} \right.$$

If  $\mathfrak{a} \cap \mathfrak{g}_\alpha \neq 0$  for some  $\alpha \in \Delta$ , then  $\mathfrak{g}_\alpha \subset \mathfrak{a}$ .  
 $\mathbb{C}h_\alpha = [\mathfrak{g}_{-\alpha}, \mathfrak{g}_\alpha] \subset \mathfrak{a}$ . So  $h_\alpha \in \mathfrak{a}$ . But  $[h_\alpha, x] = \alpha(h_\alpha) \cdot x$   
 $x \in \mathfrak{g}_\alpha \neq 0$

$h_{\alpha}, \alpha$  do not commute, but  $h_{\alpha}, \alpha \in \mathfrak{a}$ : contradiction.

So  $\mathfrak{g}$  is semisimple.

ex 5.3:  $\Delta \subset \mathfrak{h}^*$  indec if not of the form  $\Delta = \Delta_1 \cup \Delta_2$ ,  $\Delta_i \neq \emptyset$ ,  $\forall \alpha, \beta \in \Delta$ ,  $\alpha + \beta \notin \Delta \cup \{0\}$ .

1-  $\Delta$  indec  $\Rightarrow \mathfrak{g}$  simple.

[ $\mathfrak{g}$  not simple  $\Rightarrow \Delta$  decomposable.]

$\mathfrak{g} = \mathfrak{g}_1 \oplus \mathfrak{g}_2$  ,  $\mathfrak{g}_1, \mathfrak{g}_2 \neq 0$  and semisimple.  
ideals of  $\mathfrak{g}$ .

$$\mathfrak{g}_1 = \mathfrak{h}_1 \oplus \bigoplus_{\alpha \in \Delta_1} \mathfrak{g}_{1\alpha} \quad \mathfrak{g}_2 = \mathfrak{h}_2 \oplus \bigoplus_{\alpha \in \Delta_2} \mathfrak{g}_{2\alpha}$$

$$\mathfrak{g} = (\mathfrak{h}_1 \oplus \mathfrak{h}_2) \oplus \bigoplus_{\alpha \in \Delta_1} \mathfrak{g}_{1\alpha} \oplus \bigoplus_{\alpha \in \Delta_2} \mathfrak{g}_{2\alpha}.$$

$$\Delta = \underbrace{\Delta_1}_{\mathfrak{h}_1^*} \cup \underbrace{\Delta_2}_{\mathfrak{h}_2^*} \subset \mathfrak{h}^* \quad \mathfrak{h} = \mathfrak{h}_1 \oplus \mathfrak{h}_2$$

$$\mathfrak{h}^* \simeq \mathfrak{h}_1^* \oplus \mathfrak{h}_2^*.$$

$\alpha \in \Delta_1, \beta \in \Delta_2$ . Show that  $\alpha + \beta \notin \Delta \cup \{0\}$ .

$\alpha + \beta \neq 0$  since  $\mathfrak{h}_1^* \cap \mathfrak{h}_2^* = 0$  so  $\alpha, \beta$  are linearly independent.

If  $\alpha + \beta = \gamma \in \Delta = \Delta_1 \cup \Delta_2$

so for ex.  $\gamma \in \Delta_1$  and  $\alpha - \gamma = -\beta$

but  $\mathfrak{h}_1^* \cap \mathfrak{h}_2^* = (0)$ .

2-  $\Delta$  is indecomposable  $\Leftrightarrow \forall \alpha, \beta \in \Delta$ , can find  $\gamma_1, \dots, \gamma_s \in \Delta$

$$\begin{array}{ccccccc} \gamma_1 & \gamma_2 & \dots & \dots & \gamma_{s-1} & \gamma_s & \\ \parallel & & & & & \parallel & \\ \alpha & & & & & \beta & \end{array} \quad (*)$$

$$\gamma_i + \gamma_{i+1} \in \Delta \cup \{0\}$$

$\Leftarrow$

If  $\Delta = \Delta_1 \cup \Delta_2$  decomposable. Take  $\alpha \in \Delta_1, \beta \in \Delta_2$ .

If  $\exists \gamma_1 \rightarrow \gamma_s$  as in the r.h.s of (\*),

$$\alpha = \underbrace{\gamma_1}_{\in \Delta_1} \gamma_2 \overset{\exists i}{\cdot} \gamma_i \gamma_{i+1} \gamma_{i+2} \dots \gamma_s = \underbrace{\beta}_{\in \Delta_2}$$

$$\gamma_i + \gamma_{i+1} \in \Delta \cup \{0\}.$$

By def of a decomposition of  $\Delta$ , cannot have this.  
 $\rightarrow$  no path between  $\alpha$  and  $\beta$ .

have to prove  
 $\Rightarrow \exists \alpha, \beta \in \Delta$ , no path between  $\alpha$  and  $\beta \Rightarrow \Delta$  decomposable  
Assume  $\rightarrow$ .

Define  $\Delta_1 = \{ \alpha' \in \Delta \mid \exists \text{ path between } \alpha \text{ and } \alpha' \}, \ni \alpha$   
 $\Delta_2 = \{ \alpha' \in \Delta \mid \nexists \text{ path between } \alpha \text{ and } \alpha' \} \ni \beta$

$\Delta = \Delta_1 \sqcup \Delta_2$   
 $\downarrow \quad \downarrow$   
 $\alpha \quad \beta$   
Show: if  $\gamma \in \Delta_1, \delta \in \Delta_2$ ,  
 $\gamma + \delta \notin \Delta \cup \{0\}$ .

Assume  $\gamma + \delta \in \Delta \cup \{0\}$ .

$\alpha \xrightarrow{\gamma_i} \gamma + \delta \rightarrow$  path between  $\alpha$  and  $\delta$ : contradiction.  
 $\gamma + \delta \in \Delta \cup \{0\}$

so  $\gamma + \delta \notin \Delta \cup \{0\}$ . and  $\Delta = \Delta_1 \sqcup \Delta_2$  is a dec. of  $\Delta$

$\sqrt{g_{ss}} \rightarrow \Delta = \Delta_1 \sqcup \dots \sqcup \Delta_s$   
ind. root syst., canonical decomposition.

$g = g_1 \oplus \dots \oplus g_s$  ,  $g_i$  simple. ]

ex 5.4.  $V$   $\mathbb{C}$ -vspace.  $B \in (V \otimes V)^*$

1.  $\sigma_{V,B} = \{ a \in \mathfrak{gl}(V) \mid B(au, v) + B(u, av) = 0 \quad \forall u, v \in V \}$

$\mathfrak{gl}(V) \curvearrowright (V \otimes V)^* \ni \{ [ a \in \mathfrak{gl}(V), a \cdot b(u, v) = -b(av, u) - b(u, a \cdot v) ] \}$

$\sigma_{V,B} = \text{Stab}_{\mathfrak{gl}(V)}(B) = \{ a \in \mathfrak{gl}(V) \mid a \cdot B = B \}$ .

subalgebra.

2- Choose a basis of  $V$ ,  $M$  the matrix of  $B$  in this basis  
 $\{v_i\}_{1 \leq i \leq n}$  "  $(B(v_i, v_j))_{1 \leq i, j \leq n}$

$v \in V$   $v = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$   $x_i$  are coordinates of  $v$  in  $\{v_i\}$ ,  
 $u \in V$

$$B(u, v) = {}^t u B v. \in \mathbb{C}, \quad \text{transpose of } M \quad \left( \begin{smallmatrix} \leftarrow \\ \rightarrow \end{smallmatrix} \right) = a^T$$

$$\mathfrak{o}_{n, n} = \left\{ a \in \mathfrak{gl}_n(\mathbb{C}) \mid a^T M + M a = 0 \right\}$$

$M$  is symm n.d.

3- Over alg. closed field:  $\exists A \in GL_n(\mathbb{C})$  s.t.

$$A^T M A = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

"any quad form over a.c. field is equivalent to  $x_1^2 + \dots + x_n^2$ "  
 fdim  $n$ , n-rank.

4.  $M = \begin{pmatrix} & & & 1 \\ & & \ddots & \\ & 0 & & \\ 1 & & & 0 \end{pmatrix} \in \mathfrak{gl}_n(\mathbb{C})$

$\mathfrak{o}_{n, n} = \mathfrak{so}_n(\mathbb{C})$   
 orthogonal Lie algebra

$a \in \mathfrak{gl}_n$ .  $a^T M + M a = 0$

$\Leftrightarrow a + a' = 0$

$a' =$  transpose of  $a$   
 w.r.t. the antidiagonal.

$$\begin{pmatrix} a & \\ & -a \end{pmatrix}$$

$$a = \begin{pmatrix} x & y \\ z & t \end{pmatrix} = \begin{pmatrix} x & 0 \\ 0 & -x \end{pmatrix}$$

$$\begin{pmatrix} x & y \\ y & t \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} z & x \\ t & y \end{pmatrix}$$

$$M a = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x & y \\ z & t \end{pmatrix} = \begin{pmatrix} z & t \\ x & y \end{pmatrix}$$

$$\begin{pmatrix} z+z & t+x \\ t+x & y+y \end{pmatrix} = 0$$

5-  $\mathfrak{so}_2 = \left\{ \begin{pmatrix} x & 0 \\ 0 & -x \end{pmatrix} \in \mathfrak{gl}_2 \right\} \simeq \mathbb{C}$  semi not simple.

6-  $n \geq 3$ .  $\mathfrak{so}_n$  is semisimple.

$n = 2N + 1$

$$\mathfrak{h} = \left\{ \begin{pmatrix} a_1 & & & & 0 \\ & \ddots & & & \\ & & a_N & & 0 \\ & & 0 & & -a_N \\ & & & & \\ 0 & & & & -a_1 \end{pmatrix}, a_1, \dots, a_N \in \mathbb{C} \right\}$$

$\subset \mathfrak{so}_n$

$n = 2N$

$$\mathfrak{h} = \left\{ \begin{pmatrix} a_1 & & & & 0 \\ & \ddots & & & \\ & & a_N & & 0 \\ & & & & -a_N \\ & & & & \\ 0 & & & & -a_1 \end{pmatrix} \right\}$$

$\mathfrak{h}$  abelian subalgebra,  $\mathfrak{so}_n^{ss}$ , maximal.

$a_1, \dots, a_N$  s.t.  $a_1, \dots, a_N, 0, \dots, a_N, \dots, -a_1$  are distinct, take  
 $x \in \mathfrak{sl}_m$ ,  $[x, \text{diag}(a_1, \dots, a_N, 0, \dots, a_N, \dots, -a_1)] = 0 \Rightarrow x$  diagonal  
 $\rightarrow \mathfrak{h}$  maximal:  $\mathfrak{h}$  is a Cartan subalgebra of  $\mathfrak{so}_n$ .

basis of  $\mathfrak{h}^*$ :  $\epsilon_1, \dots, \epsilon_N \in \mathfrak{h}^*$  basis of  $\mathfrak{h}^*$ .  $\epsilon_i \begin{pmatrix} a_1 & & & 0 \\ & \ddots & & \\ & & a_N & \\ 0 & & & \ddots & \\ & & & & -a_1 \end{pmatrix}$

$n = 2N + 1$ .

$\epsilon_i = -\epsilon_{m+1-i}$   $\epsilon_{\frac{m+1}{2}} = 0$

Find root space decomposition of  $\mathfrak{so}_n$ ; eigenvectors for  $\mathfrak{h} \cap \mathfrak{so}_n$ .

$E_{ij} = i \begin{pmatrix} 0 & & & \\ & \ddots & & \\ & & 1 & \\ & & & \ddots & \\ & & & & 0 \end{pmatrix}$

answer:  $E_{ij} - E_{m+1-j, m+1-i}$  root:  $\epsilon_i - \epsilon_j$

$1 \leq i, j \leq n$   $i \neq j$

$\mathfrak{so}_n = \mathfrak{h} \oplus \sum_{i \neq j} \mathbb{C} \cdot (E_{ij} - E_{m+1-j, m+1-i})$

if  $i \rightsquigarrow m+1-j$   
 $j \rightsquigarrow m+1-i$

$\begin{pmatrix} & & & \\ & & & \\ & & -1 & \\ & & & \ddots & \\ & & & & -1 \end{pmatrix}$

roots of  $\mathfrak{so}_n$ :  $n = 2N + 1$   $\Delta_{\mathfrak{so}_n} = \left\{ \epsilon_i - \epsilon_j, \epsilon_i, -\epsilon_i, \epsilon_i + \epsilon_j, -\epsilon_i - \epsilon_j \mid 1 \leq i, j \leq N, i \neq j \right\}$

$\epsilon_i - \epsilon_j$   $1 \leq i, j \leq n$   
 $i \neq j$   
 $\epsilon_i - \epsilon_j$  if  $1 \leq i, j \leq N$   
 if  $j = m+1-i'$   
 $\epsilon_i + \epsilon_{j'}$   $1 \leq j' \leq N$

$n = 2N$   $\Delta_{\mathfrak{so}_n} = \left\{ \epsilon_i - \epsilon_j, \epsilon_i + \epsilon_j, -\epsilon_i - \epsilon_j \mid 1 \leq i, j \leq N, i \neq j \right\}$

$\text{Span } \Delta_{\mathfrak{so}_n} \ni \epsilon_i$   $1 \leq i \leq N$

$[\sigma_\alpha, \sigma_{-\alpha}] \stackrel{?}{=} \Phi \alpha$   $\sigma_\alpha = \mathbb{C} \cdot (E_{ij} - E_{m+1-j, m+1-i})$

$\sigma_{-\alpha} = \mathbb{C} \cdot (E_{ji} - E_{m+1-i, m+1-j})$

$\alpha = \epsilon_i - \epsilon_j$

$1 \leq i, j \leq N$   
 $i \neq j$

$$h\alpha = [E_{ij} - E_{n+1-j, n+1-i} \mid E_{ji} - E_{n+1-i, n+1-j}]$$

$$= E_{ii} + E_{n+1-j, n+1-j} - E_{jj} - E_{n+1-i, n+1-i}$$

$$\alpha = \epsilon_i - \epsilon_j$$

$$\alpha(h\alpha) = 2 \neq 0.$$

$\Rightarrow$   $so_n$  is semi simple. If  $n=2$  : something does not work.

$$i=1$$

$$j=2$$

$$n=2. \quad E_{11} + E_{22} - E_{22} - E_{11} = 0.$$

7.  $n=3$  : root system  $\Delta = \{\epsilon_1 - \epsilon_1\}$  indecomposable.  
 $\epsilon_1 - \epsilon_2$  path.

$\Rightarrow$  same root system as  $sl_2$ .

$$sl_2 \cong so_3.$$

$$so_3 = \begin{pmatrix} a & c & 0 \\ d & 0 & -c \\ 0 & -d & -a \end{pmatrix}$$

$$h = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$e = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$f = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix}$$

$\rightarrow$  set the rels of  $sl_2$

$$\begin{cases} [h, e] = 2e \\ [h, f] = -2f \\ [e, f] = h. \end{cases}$$

$n \geq 5.$

$n=2N+1. \quad \Delta so_n$

$n \geq 5$

$\alpha - \alpha$

$\epsilon_i - \epsilon_j$

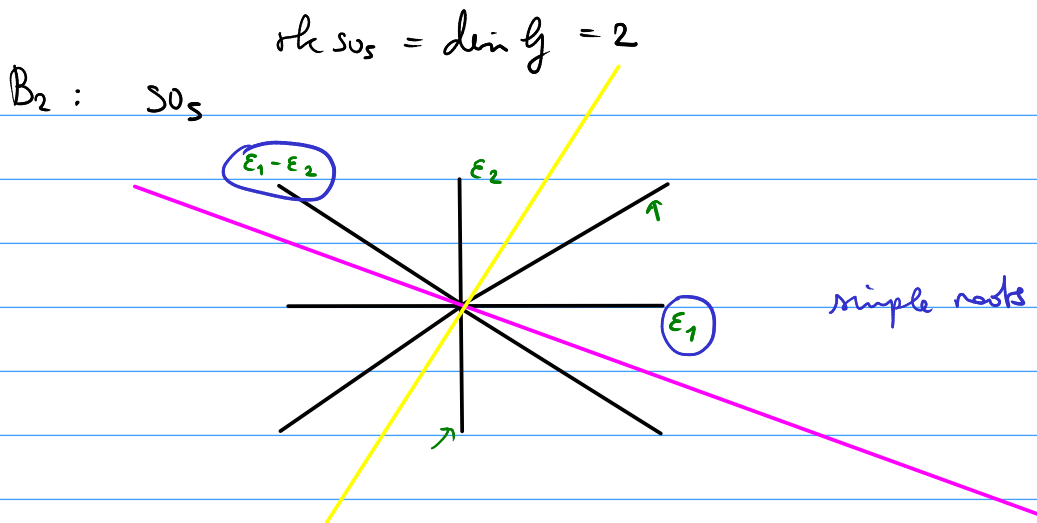
$\epsilon_i - \epsilon_j$

$\epsilon_j$

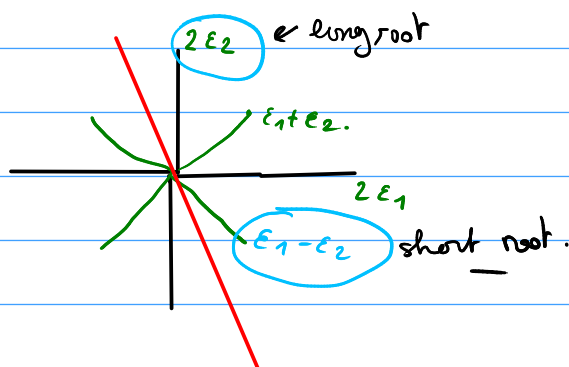
$\epsilon_i$

$\epsilon$





$C_2: sp_4$  . roots :  $\{ 2\epsilon_1, 2\epsilon_2, \epsilon_1 + \epsilon_2, -\epsilon_1 + \epsilon_2, \dots \}$



S.4  $a, b \in U_{V,B}$   $[a, b] \stackrel{?}{\in} U_{V,B}$ .

$$\begin{aligned}
 & u, v \in V \\
 & B([a, b]u, v) + B(u, [a, b]v) \\
 & \quad \parallel \quad \parallel \\
 & B(\underline{a} \underline{b} u, v) - B(\underline{b} a u, v) + B(u, \underline{a} \underline{b} v) - B(u, \underline{b} a v) \\
 & \quad \parallel \quad \parallel \\
 & \quad \quad \quad \parallel \\
 & \quad \quad \quad 0 \\
 & \quad \quad \quad = 0 \\
 & \Rightarrow [a, b] \in U_{V,B}.
 \end{aligned}$$

$V \ni \mathfrak{gl}(V)$ .

$\mathfrak{gl}(V) \cong V \otimes V \ni u \otimes v$   
 $a \in \mathfrak{gl}(V)$

$$a \cdot (u \otimes v) = au \otimes v + u \otimes av.$$

and  $\mathfrak{gl}(V) \cong V^*$ :

$$a \cdot f = f(-a \cdot)$$

$a \in \mathfrak{gl}(V)$   $f \in V^*$

$$\mathfrak{gl}(V) \cong (V \otimes V)^* : a \cdot B = -B(a \cdot, -) - B(-, a \cdot)$$



$$(a \cdot \tilde{B})(u, v) = -B(au, v) - B(u, av).$$

$$G_{V, B} = \text{Stab}_{\mathfrak{gl}(V)}(B) = \{a \in \mathfrak{gl}(V) \mid a \cdot B = 0\}$$
$$= \text{Lie algebra.}$$

$$\mathfrak{g} \begin{array}{c} \Downarrow \\ W \\ \Downarrow \\ W \end{array} . \quad \begin{array}{c} \text{Stab}_{\mathfrak{g}}(w) \\ \text{is a Lie alg of } \mathfrak{g} \\ \{a \in \mathfrak{g} \mid a \cdot w = 0\} . \end{array}$$