

On Gressman's

Affine Invariant Measures

Lecture 4

With these technical details out of the way we can finally use the construction of Theorem 1 on the Affine Curvature Tensor to obtain a density on the submanifold.

Gressman's Affine Invariant Measure

Let $f: \Sigma \rightarrow \mathbb{R}^n$ be an embedding of Σ (of dimension d); with $\Lambda_{d,n}$ the diagram introduced before, we let $Q := \# \Lambda_{d,n}$ (it plays the rôle of a homogeneous dimension).

If $\{\partial_1, \dots, \partial_d\}$ is a fixed basis of the tangent space $T_t \Sigma$ (at $t \in \Sigma$) and $X = \sum_{j=1}^d x_j \partial_j$ is a tangent vector, we write

$$M^T X = \sum_i \left[\sum_j M_{ji} x_j \right] \partial_i$$

(exactly as if we replaced ∂_i with e_j); then $\rho_M A_t^f$ is defined as before.

We define the density

$$\begin{aligned} \mu_M^t(X_1, \dots, X_d) &:= \inf_{M \in SL(\mathbb{R}^d)} \left\| \rho_M A_t^f \right\|_X^{d/Q} \\ &= \inf_{M \in SL(\mathbb{R}^d)} \left[\left(\sum_{j_1=1}^d \dots \sum_{j_Q=1}^d \left| A_t^f(M^T X_{j_1}, \dots, M^T X_{j_Q}) \right|^2 \right)^{1/2} \right]^{d/Q} \end{aligned}$$

Using the density, one then defines a measure of Σ itself by push-forward:

If $\varphi: B \subseteq \mathbb{R}^d \rightarrow \Sigma$ (B a ball) is a coordinate chart, we let

$$\int_{\varphi(B)} g d\nu_{\varphi} := \int_B g(\varphi(y)) \mu_{\varphi} \left(d\varphi(\partial_{y_1}), \dots, d\varphi(\partial_{y_d}) \right) dy_1 \dots dy_d.$$

Thus we have defined a measure ν_{φ} on the submanifold Σ . There are many things to check about this ν_{φ} , but first an obvious one (which we have already seen):

|| Claim: The functional $\Sigma \mapsto \nu_{\varphi}$ constructed above is equi-affine invariant.

Proof: Ignoring translations (clearly irrelevant), let $A \in SL(\mathbb{R}^n)$. We see directly that by linearity

$$A \mathcal{A}_t^f \left((X_{(j,k)})_{(j,k) \in \Delta_{d,n}} \right) = \det \left[\dots \begin{pmatrix} X_{(j_1)} & \dots & X_{(j_k)} \end{pmatrix} A f(t) \dots \right]$$

$$= \det \left(\dots A \begin{pmatrix} X_{(j_1)} & \dots & X_{(j_k)} \end{pmatrix} f(t) \dots \right) \leftarrow \begin{matrix} \text{(this happens} \\ \text{in every} \\ \text{column)} \end{matrix}$$

$$= \det A \cdot \mathcal{A}_t^f \left((X_{(j,k)})_{(j,k) \in \Delta_{d,n}} \right), \text{ which is enough to conclude. } \blacksquare$$

Remark: The equi-affine invariance of ν_{φ} has nothing to do with the fact that we are taking $\inf_{M \in SL(\mathbb{R}^d)}$ in the definition of ν_{φ} ! It's purely a consequence of the structure of \mathcal{A}_t^f .

Now ν_{φ} looks like a reasonable candidate, but there are many questions that need answers:

- ① Is $\nu_{\varphi} \neq 0$ ever? More in general, given a submanifold Σ , can we establish whether $\nu_{\varphi} \neq 0$ for Σ ?

To answer the first part, Gressman provides a large class of examples for which $\mu_A = \text{constant} \neq 0$; they are all of the form seen before, with polynomial coordinates of increasing degrees, but they must satisfy certain conditions (corresponding to a certain derivative vanishing).

The second part is more delicate and there isn't a definitive answer. Gressman provides a series of criteria to verify whether $\mu_A \neq 0$, with various degrees of generality and applicability. We will see one of the most interesting ones.

② | Is the measure ν_A good for our purposes, that is, L^p -smoothing and Fourier Extension/Restriction?

Let us go back to a result stated before that involved the affine invariant measure on hypersurfaces:

Theorem (endpoint L^p -smoothing for hypersurface)

Let $d\Omega_\Sigma = |K_\Sigma|^{-\frac{1}{n+1}} d\sigma_\Sigma$, where $\Sigma \subseteq \mathbb{R}^n$ is a hypersurface; then

$$\|f * d\Omega_\Sigma\|_{L^{n+1}(\mathbb{R}^n)} \lesssim \|f\|_{L^{\frac{n+1}{n}}(\mathbb{R}^n)}.$$

We make the following observation. The restricted weak-type reformulation of the inequality above is

$$\langle \mathbb{1}_E * d\Omega_\Sigma, \mathbb{1}_F \rangle \lesssim |E|^{\frac{n}{n+1}} |F|^{\frac{n}{n+1}}$$

for measurable sets E, F (notice $(n+1)' = \frac{n+1}{n}$).

If we take $E = F = R$ a given rectangle this reads

$$\langle \mathbb{1}_R * d\Omega_\Sigma, \mathbb{1}_R \rangle = \langle d\Omega_\Sigma, \mathbb{1}_R * \mathbb{1}_R \rangle \lesssim |R|^{\frac{2n}{n+1}};$$

but one can easily see that

$$\mathbb{1}_R * \mathbb{1}_R \gtrsim |R| \mathbb{1}_R,$$

and therefore

$$|R| \langle d\Omega_\Sigma, \mathbb{1}_R \rangle \lesssim |R|^{\frac{2n}{n+1}}$$

$$\Omega_\Sigma(R)$$

$$\Rightarrow \boxed{\Omega_\Sigma(R) \lesssim |R|^{\frac{n-1}{n+1}}}$$

(Recall that the dimension $\frac{\alpha}{n}$ for Oberlin's rectangular Hausdorff measure in the case of hypersurfaces was exactly $\frac{\alpha}{n} = \frac{n-1}{n+1}$.)

The above is known as a "curvature condition" for measures, and the argument given generalises to show that if one has L^p -smoothing ~~for~~ for a certain measure μ , that is

$$\|f * d\mu\|_{L^q(\mathbb{R}^n)} \lesssim \|f\|_{L^p(\mathbb{R}^n)}, \quad (q > p)$$

then it must satisfy

$$\mu(R) \lesssim |R|^{\frac{1}{p} - \frac{1}{q}},$$

which is again a curvature condition.

Remark: Fourier restriction estimates for submanifolds with measures μ similarly imply curvature conditions for μ (using Gaussians instead of rectangles).

So, the above has shown that a necessary condition for ν_{Σ} to be "useful" is that it has to be curved for some exponent. We will show that this is indeed the case: in particular, we will show that

$$\boxed{\nu_{\Sigma}^2(R) \lesssim |R|^{d/Q}} \quad (C)$$

for all rectangles $R \subseteq \mathbb{R}^n$ ($d = \dim \Sigma$, $Q = \# \Lambda_{d,n}$)

This discussion has however raised another question.

③

Are there "better" measures than ν_{Σ} to do what we want?

For example, are there measures μ that are $\gtrsim \nu_{\Sigma}$ (and much larger) but are curved with the same d/Q exponent?

The answer to this question will be essentially NO, in the sense that ν_{Σ} is the largest measure that satisfies (C), up to a multiplicative constant.

More formally, one can show that if we let

$$C_\mu := \sup_{R \text{ rectangle}} \frac{\mu(R)}{|R|^{d/Q}}$$

then for every μ such that $C_\mu < \infty$ one has

$$\mu \lesssim_{d,n} C_\mu \mathcal{V}_d.$$

④

What is the relationship between \mathcal{V}_d and the affine invariant measures for curves

$$d\Omega_\gamma = |T_\gamma|^{\frac{2}{n(n+1)}} |\gamma'(t)| dt$$

and hypersurfaces

$$d\Omega_\Sigma = |K_\Sigma|^{\frac{1}{n+1}} d\sigma_\Sigma ?$$

These two cases are luckily simple enough that we can show directly that \mathcal{V}_d actually coincides with those measures when $d=1$ (curves) or $d=n-1$ (hypersurfaces).

⑤

What is the relationship between \mathcal{V}_d and Oberlin's measure $R^\alpha|_\Sigma$?

It turns out (as one would intuitively expect) that the two measures that result from these two functionals are always comparable. However, to see this one has to ~~do~~ do some extra work - this fact indeed follows from Gressman's more recent paper "Geometric Averaging Operator and Nonconcentration Inequalities."