

# Discrete Geometry

## The (Refined) Polynomial Method

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# Generalising Joints

- Recall that, given a (multi)set of lines,  $\mathcal{L} \subset \mathbb{F}^d$ , a joint is a point of intersection of  $d$  lines in  $\mathcal{L}$  whose directions span  $\mathbb{F}^d$ .
  - Let us consider multiple multisets (families) of algebraic varieties.
- What follows is a reading of Tidor–Yu–Zhao 2020, *Joints of Varieties*, arXiv:2008.01610.
- Today I will give the intro + overview of the argument

## Definition (Multijoint)

- Let  $d \in \mathbb{N}$ , for each  $1 \leq j \leq d$ , let  $k_j, m_j \in \mathbb{N}$  and let  $n = k_1 m_1 + \dots + k_d m_d$ . For each  $1 \leq j \leq d$ , let  $\Gamma_j$  be a set of  $k_j$ -dimensional varieties.
- For each  $1 \leq j \leq d$ , let  $\gamma_j^1, \dots, \gamma_j^{m_j} \in \Gamma_j$ , and suppose

$$\bigcap_{j=1}^d \bigcap_{m=1}^{m_j} \gamma_j^m = p \in \mathbb{F}^n.$$

- If the tangent spaces  $\{T_p \gamma_j^m\}_{j,m}$  span  $\mathbb{F}^n$  then  $p$  is a  $(m_j, k_j)$ - multijoint.

## Definition (Multiplicity)

The number of tuples  $(\gamma_j^k)$  which form a multijoint at  $p$  is the multiplicity of  $p$ , denoted  $M(p)$ .

# Joints Problem

## Theorem (Joints)

Let  $\mathcal{L} \subset \mathbb{R}^d$  be a collection of lines. Then there are at most  $O(|\mathcal{L}|^{\frac{d}{d-1}})$  joints.

## Theorem (Tidor–Yu–Zhao (2020))

Let  $\Gamma_j \subset \mathbb{F}^n$  be families of  $k_j$ -varieties for each  $1 \leq j \leq d$  and let  $s = m_1 + \dots + m_d$ . Then

$$\sum_{p \in \mathbb{F}^n} M(p)^{\frac{1}{s-1}} \leq C(m_j, k_j) \prod_{j=1}^d (\deg \Gamma_j)^{\frac{m_j}{s-1}},$$

where  $\deg \Gamma_j = \sum_{\gamma_j \in \Gamma_j} \deg \gamma_j$ .

Remark:

- Dimensions  $k_1, \dots, k_d$  do not affect exponents.
- Constant is independent of the field.

# $(m_j, k_j)_{j=1}^d$ -multijoints

Examples:

- Joints problem from before. One family of lines, choose  $m$  lines.
  - $(m, 1)_{j=1}^1$ .
- Simple multijoints. As above, but with  $d$  families, choose one line from each.
  - $(1, 1)_{j=1}^d$ .
- Joints formed by  $m$   $k$ -varieties in  $\mathbb{F}^{mk}$ .
  - $(m, k)_{j=1}^1$ .
- Joints formed by a 2-plane from one family and 2 lines from another in  $\mathbb{F}^4$ .
  - $((1, 2), (2, 1))$ .

Remark:

- The degree of the varieties doesn't affect the  $(m_j, k_j)$  notation, nor the constant.

To prove:

## Theorem

Let  $\Gamma_j \subset \mathbb{F}^n$  be families of  $k_j$ -planes for each  $1 \leq j \leq d$ . Then

$$\sum_{p \in \mathbb{F}^n} M(p)^{\frac{1}{s-1}} \leq C(m_j, k_j) \prod_{j=1}^d |\Gamma_j|^{\frac{m_j}{s-1}},$$

where  $s = m_1 + \dots + m_d$ .

The content remains the same. Retaining rigour while accounting for high degree varieties steps into algebraic geometry – good to know it can be done, but not important for our purposes.

# Method for Joints (and Finite Field Kakeya)

- Use Parameter Counting to get a non-zero polynomial of low degree which vanishes over a specified set.
- Use geometry of the set to deduce additional properties of the polynomial.
- Use Vanishing Lemma (Bézout) to deduce that such a polynomial must either
  - be identically zero, or
  - have appropriately few zeros.



# What Fails?

## Parameter Counting:

- In  $\mathbb{F}^d$  we find a polynomial  $f \neq 0$  s.t.  $\deg f \lesssim |J|^{\frac{1}{d}}$ .
  - Some constraints imposed by  $J$  are redundant.
  - E.g. if  $f \in \mathbb{F}_1[x_1, \dots, x_d]$  is zero at two points then it is zero on the line they define.
  - We can improve on  $|J|$ .

## Vanishing Lemma:

- A polynomial in more than one variable can have infinitely many zeros.
  - E.g. If many points lie in a subvariety of low degree.
- Alternatively: We don't have a suitable form of Bézout's Theorem.

## Definition (Vanishing Condition)

A vanishing condition is a polynomial whose monomials are derivative evaluation maps. Alternatively, they are finite linear combinations of directional derivative evaluations.<sup>a</sup>

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<sup>a</sup>Note we use derivative evaluations, not just derivative maps.

- E.g.  $f(1, 2) = 0$ ,  $\partial_x(f(2, 3)) = 0$ ,  $(\partial_{xxy} - \partial_{yyx})f(0, 1) = 0$ .
- Carefully choose vanishing conditions so that a vanishing lemma holds.
- Using few enough to that a Bézout substitute is automatic.

## Key Idea 2

Consider space  $\mathbb{F}_3[t]$ , and vanishing conditions of 0-th order. We can find a non-zero  $f \in \mathbb{F}_3[t]$  that satisfies up to 3 distinct 0-th order vanishing conditions, but not more.

Question:

- What can we say about the 3 distinct conditions that we cannot say about 4 or more?

Answer:

- They are linearly independent.

Conclusion:

- Interpret space of vanishing conditions as the vector space that is dual to  $\mathbb{F}_3[t]$ , or more generally  $\mathbb{F}_\lambda[x_1, \dots, x_n]$ .
- Now the number of vanishing conditions we need to consider is at most  $\dim \mathbb{F}_\lambda[x_1, \dots, x_n]$  – this will play the rôle of Bézout.

- To cycle through all the points and orders of vanishing in  $J$ , and accumulate vanishing conditions at each  $p \in J$ .
- But, we need to order the sets of pairs  $(p, r)$  in a sensible way.
  - Introduce handicaps and priority orders.
- Start by endowing the set of points  $\mathcal{P}$  with some *preassigned order* so we can compare  $(>, <, =)$  any two  $p, p' \in \mathcal{P}$ .

# Handicaps and Priority Order

We will assign vanishing conditions by cycling through a finite set of points  $\mathcal{P} \subset \mathbb{F}^n$ . Let  $\alpha : \mathcal{P} \rightarrow \mathbb{Z}$ . The function  $\alpha$  is referred to as a *handicap*.

We assign a total ordering, called the *priority order*, to the set  $\mathcal{P} \times \mathbb{N}$ . First of all, give  $\mathcal{P}$  a preassigned order (any will do), and we say  $(p, r) \prec (p', r')$  if

- $r - \alpha_p < r' - \alpha_{p'}$ ,<sup>1</sup> or
- $r - \alpha_p = r' - \alpha_{p'}$  and  $p$  comes before  $p'$  in the preassigned order.

Remark:

- The priority order does not change under  $\alpha \mapsto \alpha + c$  for any constant  $c \in \mathbb{Z}$ .

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Adopt the convention  $0 \in \mathbb{N}$  - we will need 0-th order derivatives later.

<sup>1</sup>Large handicap allows  $r$ -th occurrence of  $p$  to appear early.

# Example

Consider a set of points  $\{a < b < c < d < e\}$  with handicaps  $0, 1, 3, -1, 0$ , respectively. This can be represented by

$$c|c|bc|abce|acbde|abcde \dots$$

That is  $(c, 1)$  represented by the 1-st occurrence of  $c$ , etc. I.e.

$$(c, 1) \prec (c, 2) \prec (b, 1) \prec (c, 3) \prec (a, 1) \prec (b, 2) \prec (c, 4) \prec (e, 1) \prec \dots$$

# Pause for Breath/Questions



# Choosing Vanishing Conditions

- Choose  $\lambda \in \mathbb{N}$  which we fix. Let  $\gamma$  be a  $k$ -plane, and for every  $r \in \mathbb{N}$ , let  $\mathbb{D}_{p,\gamma}^r$  be the set of derivative maps with directions parallel to  $T_p\gamma$  of order at most  $r$ .<sup>2</sup>
- Let  $\mathbb{B}_{p,\gamma}^r(\lambda)$  denote the subspace of linear operators on  $\mathbb{F}_\lambda[x_1, \dots, x_k]$  of the form  $f \mapsto Df(p)$  for  $D \in \mathbb{D}_{p,\gamma}^r$ .

For convenience,  $\mathbb{D} \leftrightarrow$  derivatives, and  $\mathbb{B} \leftrightarrow$  basis for linear functionals.

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<sup>2</sup>Note that  $T_p\gamma$  is independent of  $p$  in this special case of planes.



# Choosing Vanishing Conditions

For each  $\gamma$ , for each  $(p, r) \in (\mathcal{P} \cap \gamma) \times \mathbb{N}$ , we choose a set

$$\mathcal{B}_{p,\gamma}^r(\alpha, \lambda) \subset \mathbb{B}_{p,\gamma}^r(\lambda).$$

We fixed  $\alpha, \lambda$  and now  $\gamma$  so we may suppress them. The above now reads  $\mathcal{B}_p^r \subset \mathbb{B}_p^r$ .

Suppose we are at step  $(p, r)$ , and we have chosen  $\mathcal{B}_{p'}^{r'}$  for each  $(p', r') \prec (p, r)$  so that

- The sets  $\mathcal{B}_{p'}^{r'}$  are disjoint, and
- $\cup_{(p',r') \prec (p,r)} \mathcal{B}_{p'}^{r'}$  is a basis for  $\text{span} \left( \cup_{(p',r') \prec (p,r)} \mathbb{B}_{p'}^{r'} \right)$ .

Now choose  $\mathcal{B}_p^r$ , disjoint from every previous  $\mathcal{B}_{p'}^{r'}$ , and

$$\text{span} \left( \cup_{(p',r') \preceq (p,r)} \mathcal{B}_{p'}^{r'} \right) = \text{span} \left( \cup_{(p',r') \prec (p,r)} \mathbb{B}_{p'}^{r'} \right).$$

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Fixed  $p, \alpha, \lambda, \gamma$ .

# Choosing Vanishing Conditions

Remark:

- Although we have freedom to choose *which* elements we choose to include in  $\mathcal{B}_p^r$ , we do not have freedom on *how many* we add.
- Eventually,  $\mathcal{B}_p^r$  will be empty as  $r$  exceeds  $\lambda$ .

By the form of the sets  $\mathbb{B}_p^r$ , we can choose corresponding sets of derivatives<sup>3</sup>  $\mathcal{D}_{p,\gamma}^r(\alpha, \lambda) = \mathcal{D}_p^r$  which realise the basis elements in each  $\mathcal{B}_p^r$ .

Let

$$\mathcal{B}_{p,\gamma}(\alpha, \lambda) := \cup_{r \in \mathbb{N}} \mathcal{B}_p^r, \quad \text{and} \quad \mathcal{D}_{p,\gamma}(\alpha, \lambda) := \cup_{r \in \mathbb{N}} \mathcal{D}_p^r.$$

By construction

$$\sum_{p \in \gamma \cap \mathcal{P}} |\mathcal{B}_{p,\gamma}(\alpha, \lambda)| = \dim \mathbb{F}_\lambda[x_1, \dots, x_k] = \binom{\lambda + k}{k}.$$

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<sup>3</sup>Think of usual derivative over  $\mathbb{R}$ . For arbitrary  $\mathbb{F}$ , this is generalised by the Hasse derivative.

Fixed  $p, \alpha, \lambda, \gamma$ .

# What Was The Point of the Construction

Given our fixed handicap  $\alpha$ , for every  $1 \leq j \leq d$ ,  $\gamma_j \in \Gamma_j$  and  $p \in \gamma_j \cap J$ , we now have numbers

$$g_j(p, \gamma, \alpha, \lambda) = g_j(p, \gamma) := \frac{1}{\binom{\lambda+k_j}{k_j}} |\mathcal{B}_{p,\gamma}(\alpha, \lambda)|.$$

We will show that for any  $G : J \rightarrow \mathbb{R}_{\geq 0}$ , there is a special handicap  $\alpha$  so that, with sufficiently large  $\lambda$ ,

$$\frac{1}{G(p)^d} \prod_{(\gamma_j^m)_{j,m} \in \mathcal{M}(p)} \left( \prod_{j,m} g_j(p, \gamma_j^m) \right)^{\frac{1}{M(p)}} = O_{m_j k_j}(1)$$

for every joint  $p$ , where  $\mathcal{M}(p)$  is the set of all possible tuples  $(\gamma_j^m)_{j,m}$  which form a multijoint at  $p$ , and has cardinality  $M(p)$ .

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Fixed  $\alpha, \lambda$ , relaxed  $p, \gamma$ .

# What is special about this?

Let  $s = m_1 + \dots + m_d$ . Then this is equivalent to:

$$\left( \prod_{(\gamma_j^m)_{j,m \in \mathcal{M}(p)}} \left( \prod_{j,m} g_j(p, \gamma_j^m) \right)^{\frac{1}{M(p)}} \right)^{\frac{1}{s}} \sim_d G(p).$$

Note that this may be satisfied by additionally insisting that  $g_j(p, \gamma_j^m) = 0$  whenever  $p \notin \gamma_j^m$ .

Recall, by construction, that a Bézout-type equality holds:

$$\sum_{p \in J \cap \gamma_j^m} g_j(p, \gamma_j^m) = \frac{1}{\binom{\lambda+k_j}{k_j}} \sum_{p \in J \cap \gamma_j^m} |\mathcal{B}_{p, \gamma_j^m}(\alpha, \lambda)| = 1$$

for all  $\gamma_j^m \in \Gamma_j$  for all  $1 \leq j \leq d$ .

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This may ring a bell if you attended Brascamp–Lieb inequalities.

# We Will Show

Want to show,

$$\sum_{p \in \mathbb{F}^n} M(p)^{\frac{1}{s-1}} \lesssim \prod_{j=1}^d |\Gamma_j|^{\frac{m_j}{s-1}},$$

or, equivalently,

$$\left\| M^{\frac{1}{s}} \right\|_{\ell^{\frac{s}{s-1}}(\mathcal{J})} \lesssim \prod_{j=1}^d |\Gamma_j|^{\frac{m_j}{s}}.$$

So we will show that for  $G$  with  $\|G\|_s = 1$ ,

$$\sum_{p \in \mathcal{J}} M(p)^{\frac{1}{s}} G(p) \lesssim \prod_{j=1}^d |\Gamma_j|^{\frac{m_j}{s}}.$$

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Tidor–Yu–Zhao use the maximising  $G$ , but this ready more easily in my opinion.

$$\begin{aligned}
 \sum_{p \in J} M(p)^{\frac{1}{s}} G(p) &\lesssim \sum_{p \in J} \left( M(p) \prod_{\mathcal{M}(p)} \left( \prod_{j,m} g_j(p, \gamma_j^m) \right)^{\frac{1}{M(p)}} \right)^{\frac{1}{s}} \\
 &\leq \sum_{p \in J} \left( \sum_{(\gamma_j^m)_{j,m \in \mathcal{M}(p)}} \prod_{j,m} g_j(p, \gamma_j^m) \right)^{\frac{1}{s}} \\
 &\leq \sum_{p \in J} \left( \sum_{(\gamma_j^m)_{j,m \in \Gamma_1^{m_1} \times \dots \times \Gamma_d^{m_d}}} \prod_{j,m} g_j(p, \gamma_j^m) \right)^{\frac{1}{s}} \\
 &= \sum_{p \in J} \left( \prod_{j,m} \sum_{\gamma_j \in \Gamma_j} g_j(p, \gamma_j) \right)^{\frac{1}{s}}
 \end{aligned}$$

# More Symbol Pushing

$$\begin{aligned} \sum_{p \in J} \left( \prod_{j,m} \sum_{\gamma_j \in \Gamma_j} g_j(p, \gamma_j) \right)^{\frac{1}{s}} &\leq \prod_{j,m} \left( \sum_{p \in J} \sum_{\gamma_j \in \Gamma_j} g_j(p, \gamma_j) \right)^{\frac{1}{s}} \\ &= \prod_j \left( \sum_{\gamma_j \in \Gamma_j} \sum_{p \in J} g_j(p, \gamma_j) \right)^{\frac{m_j}{s}} \\ &= \prod_j \left( \sum_{\gamma_j \in \Gamma_j} 1 \right)^{\frac{m_j}{s}} \\ &= \prod_j |\Gamma_j|^{\frac{m_j}{s}}. \end{aligned}$$

We will see the detail of the extension to the Polynomial Method:

- Formally understand how the numbers  $g_j(p, \gamma, \alpha, \lambda)$  vary with respect to  $\alpha$ .
- Establish new “bespoke” Vanishing Lemma.
- Prove existence of nice handicap.