

**2018/19 Semester 2**  
**Stochastic Control and Dynamic Asset Allocation**  
**Problem Sheet 3 - Friday 14th February 2020<sup>1</sup>**

**Exercise 3.1.** For any  $(t, x) \in [0, T] \times \mathbb{R}$ , define the stochastic process  $(X_s^{t,x})_{s \in [t, T]}$  as the solution to the SDE

$$dX_s^{t,x} = b(X_s^{t,x}) ds + \sigma(X_s^{t,x}) dW_s, \quad \forall s \in [t, T], \quad X_t = x.$$

Let  $\mathbb{E}^{t,x}[\cdot] := \mathbb{E}[\cdot | X_t = x]$ . Define a function  $v = v(t, x)$  as

$$v(t, x) = e^{-r(T-t)} \mathbb{E}^{t,x} [g(X_T)] \quad \forall (t, x) \in [0, T] \times \mathbb{R}.$$

Assume that  $v \in C^{1,2}([0, T] \times \mathbb{R})$  and that  $(e^{-rs} \sigma(s, X_s) \partial_x v(s, X_s))_{s \in [t, T]} \in L^2([0, T] \times \mathbb{R})$ . Show that

$$\begin{aligned} \partial_t v + b \partial_x v + \frac{1}{2} \sigma^2 \partial_{xx} v - rv &= 0 \quad \text{on } [0, T] \times \mathbb{R}, \\ v(T, \cdot) &= g \quad \text{on } \mathbb{R}. \end{aligned}$$

**Exercise 3.2 (Unattainable optimizer).** Here is a simple example in which no optimal control exists, in a finite horizon setting,  $T \in (0, \infty)$ . Suppose that the state equation is

$$dX_s = \alpha_s ds + dW_s \quad s \in [t, T], \quad X_t = x \in \mathbb{R}.$$

A control  $\alpha$  is admissible ( $\alpha \in \mathcal{A}$ ) if:  $\alpha$  takes values in  $\mathbb{R}$ , is  $(\mathcal{F}_t)_{t \in [0, T]}$ -adapted, and  $\mathbb{E} \int_0^T \alpha_s^2 ds < \infty$ .

Let  $J(t, x, \alpha) := \mathbb{E}[|X_T^{t,x,\alpha}|^2]$ . The value function is  $v(t, x) := \inf_{\alpha \in \mathcal{A}} J(t, x, \alpha)$ . Clearly  $v(t, x) \geq 0$ .

- i) Show that for any  $t \in [0, T]$ ,  $x \in \mathbb{R}$ ,  $\alpha \in \mathcal{A}$  we have  $\mathbb{E}[|X_T^{t,x,\alpha}|^2] < \infty$ .
- ii) Show that if  $\alpha_t := -cX_t$  for some constant  $c \in (0, \infty)$  then  $\alpha \in \mathcal{A}$  and

$$J^\alpha(t, x) = J^{cX}(t, x) = \frac{1}{2c} - \frac{1 - 2cx^2}{2c} e^{-2c(T-t)}.$$

*Hint:* with such an  $\alpha$ , the process  $X$  is an Ornstein-Uhlenbeck process, see an earlier exercise.

- iii) Conclude that  $v(t, x) = 0$  for all  $t \in [0, T]$ ,  $x \in \mathbb{R}$ .
- iv) Show that there is no  $\alpha \in \mathcal{A}$  such that  $J(t, x, \alpha) = 0$ . *Hint:* Suppose that there is such a  $\alpha$  and show that this leads to a contradiction.

---

<sup>1</sup>Last updated 14th February 2020