

Lec 6: 24 / 03 / 21 (Wed)

①

Back to ① Itô approach

$$i \partial_t U - \partial_x^2 U + |U|^2 U = \Phi \xi \quad \text{on } \mathbb{T}$$

$P_{\leq N} =$ spatial freq cutoff onto freq $\{|m| \leq N\}$
(sharp cutoff, smooth cutoff)

We consider the finite dim'l approximation:

$$i \partial_t U_N - \partial_x^2 U_N + P_{\leq N} (|U_N|^2 U_N) = \Phi_N \xi$$

$$\bullet \quad \underline{U_N = P_{\leq N} U_N} \quad , \quad \Phi_N = P_{\leq N} \circ \Phi$$

\Rightarrow Write on the Fourier side

$$i d \hat{U}_N(m) = (-m^2 \hat{U}_N(m) + \overbrace{P_{\leq N} (|U_N|^2 U_N)(m)}^{\text{nonlinear term}}) dt + \hat{\Phi}_N(m) d\beta_n \quad \underline{|m| \leq N}$$

⇐ a finite dim'l system of SPDEs

for $(p_n, q_n)_{|n| \leq N}$

(2)

⇒ Apply Ito's lemma. (should check U_N is adapted.)

· Since we do not know if U_N exists globally in time, we need to use a stopping time argument.

Fix a target time $T \gg 1$.

Then, let τ be a stopping time s.t.

$$0 < \tau \leq \min(T, T_{\max}), \quad \text{a.s.}$$

where $T_{\max} = T_{\max}(\omega)$ is the maximal time of existence.

⇒ insert $\mathbb{1}_{[0, \tau]}(t)$ to the $d\hat{u}_N(t)$ equation.

and apply Ito's lemma.

(On \mathbb{R}^d , also insert a cutoff in size on the nonlinearity (3)
 $O\left(\frac{\|u\|}{R}\right)$.

• By the LWP argument, we have

$$\|U_N - u\|_{X_{\text{local}}^{0, 3/8}} \wedge C_{T_{\text{local}}} L_x^2 \rightarrow 0$$

$T_{\text{local}} = T_{\text{local}}(w) = \text{local existence time.}$

\Rightarrow verify Ito's lemma for u (with a stopping time.)

(de Bouard - Debussche '03
Oh - Okamoto '20

Back to (2): 3-d defocusing cubic SNLW on \mathbb{T}^3

(4)

$$\partial_t^2 u + (1-\Delta)u + u^3 = \phi \Xi$$

$$\phi \in \mathcal{HS}(L^2; H^{s-1})$$

$s > 0$

Write $u = \Psi + v$.

$$\Rightarrow \partial_t^2 v + (1-\Delta)v + (v + \Psi)^3 = 0.$$

$$\Psi \in L_T^\infty L_x^\infty$$

$$= v^3 + \underline{3v^2\Psi + 3v\Psi^2 + \Psi^3}.$$

• If $\Psi \equiv 0$, then the energy for $(v, \partial_t v)$

$$E(v, \partial_t v) = \frac{1}{2} \int |\nabla v|^2 dx + \frac{1}{2} \int (\partial_t v)^2 dx + \frac{1}{4} \int v^4 dx$$

is conserved.

(5)

$$\partial_t E(v, \partial_t v)$$

Fix good ω .

$$= \int \partial_t v \left(\partial_t^2 v + (1-\Delta)v + \cancel{v^3} \right) dx$$

use eqn

$$= -\cancel{v^3} - 3v^2\Phi - 3v\Phi^2 - \Phi^3$$

$$\leq C \|\Phi\|_{L_T^\infty L_x^\infty} \underbrace{\left(\int (\partial_t v)^2 dx \right)^{1/2} \left(\int v^4 dx \right)^{1/2}}_{\approx E(v, \partial_t v)}$$

$$+ C \|\Phi\|_{L_T^\infty L_x^6}^{1/2} \left(\int (\partial_t v)^2 dx \right)^{1/2}$$

$$\leq C(\Phi, T) \left(1 + E(v, \partial_t v) \right).$$

\Rightarrow Apply Gronwall's inequality.

$$\Rightarrow \sup_{t \in [0, T]} \|(v(t), \partial_t v(t))\|_{\mathcal{H}^1} \leq C(\omega, T) < \infty, \text{ a.s.}$$

③ Invariant measure argument.

⑥

Consider NLW (defocusing, $k \in 2N+1$)

$$(NLW) \quad \partial_t^2 u + (-\Delta)u + u^k = 0$$

- NLW is a Hamiltonian equation.

$$\partial_t \begin{pmatrix} u \\ \partial_t u \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \partial E / \partial u \\ \partial E / \partial (\partial_t u) \end{pmatrix}$$

$$\left(\begin{array}{l} \partial p_n = \frac{\partial H}{\partial q_n} \\ \partial q_n = -\frac{\partial H}{\partial p_n} \end{array} \right) \Leftrightarrow \partial_t \begin{pmatrix} p_n \\ q_n \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \partial H / \partial p_n \\ \partial H / \partial q_n \end{pmatrix}$$

$$E = E(u, \partial_t u) = \frac{1}{2} \int |\nabla u|^2 + \frac{1}{2} \int |\partial_t u|^2 + \frac{1}{k+1} \int u^{k+1}$$

\Rightarrow " $du \, d(\partial_t u)$ " is invariant under the flow.

\uparrow
does not exist.

• Also, $E(u, \partial_t u)$ is conserved under the NLW dynamics. (7)

→ Gibbs measure

$$d\mu(u, \partial_t u) = Z^{-1} e^{-E(u, \partial_t u)} d u d(\partial_t u)$$

should be invariant

massive Gaussian free field

$$\underbrace{e^{-\frac{1}{k+1} \int u^{k+1} dx}}_{\text{weight.}} \underbrace{e^{-\frac{1}{2} \|u\|_{H^1}^2}}_{\text{massive Gaussian free field}} du$$

(8)

$$e^{-\frac{1}{2} \|\partial_t u\|_{L^2}^2} d(\partial_t u)$$

spatial white noise (measure)

Gaussian measures on $\mathcal{D}'(\mathbb{T}^d)$

$$d\mu_S = Z^{-1} e^{-\frac{1}{2} \|u\|_{H^S}^2} du$$

$$\Leftrightarrow d\mu_{S,N} = Z_N^{-1} e^{-\frac{1}{2} \|P_{\leq N} u\|_{H^S}^2} d(P_{\leq N} u)$$

sharp freq cut-off.

measure on $E_N = \text{span}\{e_n, |n| \leq N\}$.

$$= Z_N^{-1} \prod_{|n| \leq N} e^{-\frac{1}{2} \frac{\langle m \rangle^{2s} |\hat{u}_m|^2}{|g_n|^2}} d\hat{u}_m$$

Lebesgue on $\mathbb{C} \cong \mathbb{R}^2$

Under $\mu_{S,N}$, we have

$$U_N(x) := \sum_{|n| \leq N} \frac{g_n(\omega)}{\langle n \rangle^s} e^{in \cdot x}$$

Take $N \rightarrow \infty$.

$\{g_n\}$, indep, standard \mathbb{C} -valued Gaussian r.v.'s.

- my course from 2017
- Also mini-courses
- Kuo : Gaussian meas in Banach sp.
- Janson
- Nuolait

$N \geq M \geq 1$

$$\mathbb{E}[\|u_N - u_M\|_{H^\sigma}^2] = \sum_{M < |n| \leq N} \frac{\langle n \rangle^{2\sigma} \mathbb{E}[|g_n|^2]}{\langle n \rangle^{2s}}$$

(9)

$$= \sum_{M < |n| \leq N} \langle n \rangle^{2\sigma - 2s} \rightarrow 0$$

iff $2\sigma - 2s < -d$

$$\Leftrightarrow \boxed{\sigma < s - \frac{d}{2}}$$

$\{u_N\}_{N \in \mathbb{N}}$ forms a Cauchy seq in $L^2(\Omega; H^\sigma(\mathbb{T}^d))$
(also in $L^p(\Omega; H^\sigma(\mathbb{T}^d))$, $p < \infty$)

\Rightarrow limit:

$$\omega \in \Omega \longmapsto u(x) = \sum_{n \in \mathbb{Z}^d} \frac{g_n(\omega)}{\langle n \rangle^s} e^{in \cdot x}$$

$$\mu_s = \lim_{N \rightarrow \infty} \mu_{s,N}$$

= induced probability measure under this map = $P \circ u^{-1}$.

Moral: μ_s is NOT a probability measure on $H^s(\mathbb{T}^d)$ (10)

and we needed to enlarge the space to H^σ , $\sigma < s - \frac{d}{2}$

ex: $W^{\sigma,p}$, $\sigma < s - \frac{d}{2}$

$$B = e^\sigma = B_{\infty, \infty}^\sigma$$

Also, Fourier-Lebesgue spaces $FL^{\sigma,p}$, $\sigma < s - \frac{d}{p}$.

and we say $(\mu_s, H^s, \underline{B})$ is an abstract Wiener space.

$d=1$

Gibbs measure for NLW

$$d\rho = Z^{-1} \underbrace{e^{-\frac{1}{k+1} \int u^{k+1} dx}}_{\text{depends only on } u} d\mu_1 \otimes d\mu_0(u, \lambda u)$$

depends only on u

$$u \in H^{\frac{1}{2}-}(\mathbb{T}), \text{ a.s.} \Rightarrow \text{Sob} \quad u \in L_x^r, \text{ a.s. } r < \infty.$$

$$\Rightarrow \underset{\text{a.s.}}{0} < e^{-\frac{1}{k+1} \int u^{k+1} dx} \leq 1$$

(11)

$$\Rightarrow e^{-\frac{1}{k+1} \int u^{k+1} dx} \in L^p(\mu_1) \quad p \leq \infty$$

and a.s. positive

$$\Rightarrow \rho \sim \mu_1 \otimes \mu_0$$

↑ equivalent (i.e. \Leftarrow and \Rightarrow)

ρ is a prob measure on $H^{\frac{1}{2}-}(\mathbb{T}) \times H^{-\frac{1}{2}-}(\mathbb{T})$.

Aside: If $L(v) = \mu_0$, then

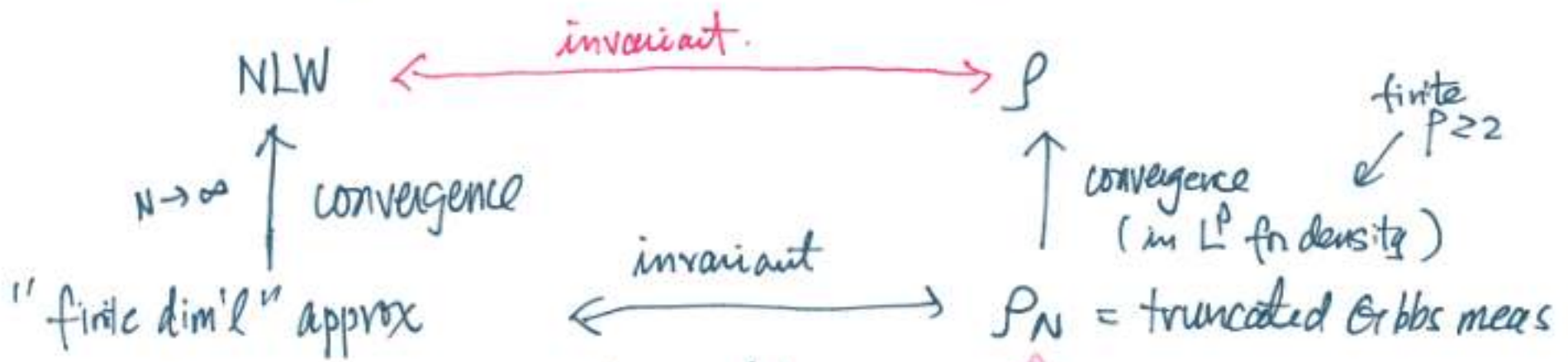
$$v = \sum_{n \in \mathbb{Z}^d} g_n e^{in \cdot x} \Leftrightarrow \text{spatial white noise}$$

↙ same intensity of randomness at each freq.

$$\text{Also, } \mathbb{E}[v(x)v(y)] = \sum_{n \in \mathbb{Z}^d} e^{in \cdot (x-y)} = \delta_0(x-y)$$

Bourgain '94

Bourgain's invariant measure argument.



$$\partial_t^2 u_N + (1-\Delta) u_N + P_{\leq N}((P_{\leq N} u)^k) = 0$$

$$dP_N = Z_N^{-1} e^{-\frac{1}{k+1} \int (P_{\leq N} u)^{k+1}} d\mu_1(x) d\mu_0(u, \partial_t u)$$

low freq ($|m| \leq N$): truncated Gibbs \Leftarrow finite dim'l Hamiltonian system

high freq : Gaussian measure.
(invariant under lin dynamics)

Main idea: Use the invariance of \mathcal{I}_N for the truncated dynamics. (for $(u_N, \partial_t u_N)$.)

N fixed Prop: Given $T > 0, \epsilon > 0, \exists \Omega_{N,T,\epsilon} \subset \Omega$

st. ① $\mathcal{I}_N(\Omega_{N,T,\epsilon}^c) < \epsilon$

② For each $w \in \Omega_{N,T,\epsilon}$, the soln $(u_N^w, \partial_t u_N^w)$ exists on $[-T, T]$ AND

$\sup_{-T \leq t \leq T} \|(u_N(t), \partial_t u_N(t))\|_{\mathcal{H}^1} \lesssim (\log \frac{1}{\epsilon})^{1/2}$
indep of N .

Pf: Fix $K \gg 1$.

Set $\Omega_{N,T,\epsilon} = \bigcap_{j=-\lceil T/\delta \rceil}^{\lceil T/\delta \rceil} \Phi_N(-j\delta) B_K,$

$\Phi_N(t): (u_0, u_1) \mapsto (u(t), \partial_t u(t))$
 $\mathcal{H}^{1/2-}$
 $\mathcal{H}^{1/2-}$

where $B_K =$ ball of radius K in $\mathcal{H}^{1/2-}(\mathbb{T})$

$\delta \sim K^{-\theta}$ local existence time for initial data of size K .

$$\textcircled{1} \quad \rho_N(\Omega_{N,T,\varepsilon}^c) \leq \sum_{i=-\lceil T/\delta \rceil}^{\lceil T/\delta \rceil} \rho_N(\Phi_N(-i\delta) B_K^c) \quad \textcircled{14}$$

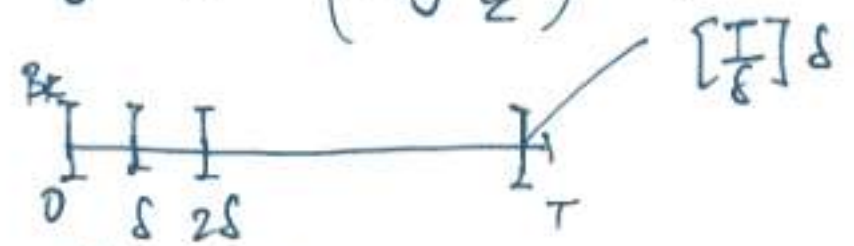
ρ_N invariant under Φ_N

$$\sim \frac{T}{\delta} \rho_N(B_K^c) \stackrel{c.s.}{\lesssim} (\mu_1 \otimes \mu_0(B_K^c))^{1/2}$$

$$\lesssim T K^\theta \underbrace{e^{-cK^2}}_{\approx e^{-c'K^2}} < \varepsilon$$

by choosing $K \sim (\log \frac{T}{\varepsilon})^{1/2}$

$\textcircled{2}$



By LWP argument, we have $\sup_{-T \leq t \leq T} \|(u_N(t), \partial_x u_N(t))\|_{H^{1/2}} \leq CK$.

$\sim (\log \frac{T}{\varepsilon})^{1/2}$
indep of N .

□

- The set $\Omega_{N,T,\varepsilon}$ depends on N
but the constants in the bd are indep of N .
- \Rightarrow can deduce the same log bound for true soln $(u, \partial_t u)$
(by a PDE approx argument.) \Rightarrow a.s GWP.
- i.e. used an invariant measure in place of a conservation law.