



(B3)  $\|B(u,v)\|_{H^{-3}} \lesssim \|u\|_{L^2} \|v\|_{L^2}$ .

proof: For  $w \in H^3$ ,

$$|\langle B(u,v), w \rangle| = |\langle B(u,w), v \rangle| = \int_{L^2} |u| \cdot |\nabla w| \cdot |v| dx$$

$$\lesssim \|u\|_{L^2} \|v\|_{L^2} \|w\|_{H^2+\epsilon} \quad \square$$

(B4)  $u, v \in \mathcal{X}_T$ ,  $\int_0^T \langle Lu(t), v(t) \rangle dt = - \int_0^T \langle \nabla u(t), \nabla v(t) \rangle dt$  ← move  $\nabla$  to  $v$   
 and  $\int_0^T \langle \partial_t u(t), u(t) \rangle dt = \frac{1}{2} (\|u(t)\|_{L^2}^2 - \|u(0)\|_{L^2}^2)$   
 •  $\nabla v = v$   
 • integration by parts

(B5)  $(u_1, u_2, u_3) \mapsto \langle B(u_1(t), u_2(t)), u_3(t) \rangle$   
 $\mathcal{X}_T \times \mathcal{X}_T \times \mathcal{X}_T \longrightarrow L^1_T$

proof: claim:  $\mathcal{X}_T \subset L^4_T H^{1/2}$ .

$$\|u\|_{L^4_T H^{1/2}}^4 = \int_0^T \|u(t)\|_{H^{1/2}}^4 dt$$

$$\lesssim \|u(t)\|_{L^2}^2 \|u(t)\|_{H^1}^2$$

$$\lesssim \|u\|_{L^\infty_T L^2_x}^2 \|u\|_{L^2_T H^1_x}^2$$

$$\lesssim \|u\|_{\mathcal{X}_T}^4$$

interpolation:  
 $S = \theta S_1 + (1-\theta) S_2$   
 $\|f\|_{H^S} \lesssim \|f\|_{H^{S_1}}^\theta \|f\|_{H^{S_2}}^{1-\theta}$

$$\int_0^T \langle B(u_1(t), u_2(t)), u_3(t) \rangle dt \stackrel{(B2) \& \text{H\"older}}{\lesssim} \|u_1\|_{L^4_T H^{1/2}} \|u_2\|_{L^4_T H^{1/2}} \|u_3\|_{L^2_T H^1}$$

$$\lesssim \|u_1\|_{\mathcal{X}_T} \|u_2\|_{\mathcal{X}_T} \|u_3\|_{\mathcal{X}_T} \quad \square$$

(NSE)  $\begin{cases} \partial_t u - Lu + B(u) = f \\ u|_{t=0} = u_0 \in L^2_{df} \end{cases}$ ,  $f = \Pi f \in L^2_T H^{-1}$ ,  $u \in \mathcal{X}_T, \forall T > 0$

Theorem: Given  $u_0 \in H = L^2_{df}$ ,  $\exists!$  global solution  $u$  to (NSE) with  $u|_{t=0} = u_0$  and

$$\sup_{0 \leq t \leq T} (\|u(t)\|_{L^2}^2 + \int_0^t \|u(t')\|_{H^1}^2 dt') \leq \|u_0\|_{L^2}^2 + \int_0^T \|f(t)\|_{H^{-1}}^2 dt, \quad \forall T > 0$$

proof: Fix  $T > 0$  and work on  $[0, T]$ .

① uniqueness: Suppose  $\exists$  two solutions  $u, v \in \mathcal{X}_T$ . Let  $w = u - v$ .

$$\Rightarrow \partial_t w - Lw + B(w, w) + B(v, w) = 0.$$

Multiply by  $w$  and integrate in  $x$ , in  $t$ .

$$|\langle B(v, w), w \rangle| \stackrel{(B1)}{=} 0$$

$$|\langle B(w, w), w \rangle| \stackrel{(B1)}{=} |\langle B(w, w), u \rangle| \stackrel{(B2)}{\leq} c \|w\|_{H^{1/2}}^2 \|u\|_{H^1}$$

$$\leq c \|w\|_{L^2} \|w\|_{H^1} \|u\|_{H^1}$$

$$\text{Cauchy} \leq \frac{1}{2} \|w\|_{H^1}^2 + c \|w\|_{L^2}^2 \|u\|_{H^1}^2$$

$$\Rightarrow \frac{d}{dt} \|w\|_{L^2}^2 + 2\|w\|_{H^1}^2 = -2 \langle B(w,u), w \rangle \leq \|w\|_{H^1}^2 + c \|w\|_{L^2}^2 \|u\|_{H^1}^2$$

$$\Rightarrow \frac{d}{dt} \|w\|_{L^2}^2 \leq c \|w\|_{L^2}^2 \|u\|_{H^1}^2$$

Gronwall

$$\Rightarrow \|w(t)\|_{L^2}^2 \leq e^{c \int_0^t \|u(t')\|_{H^1}^2 dt'} \|w(0)\|_{L^2}^2$$

= 0 = 0

⚠ This result also gives stability of solutions.

## ② Existence

Step 1: A priori bound

Suppose  $u$  is a smooth solution to (NSE).

Multiply by  $u$  and integrate.

$$\Rightarrow \frac{1}{2} \frac{d}{dt} \|u(t)\|_{L^2}^2 = \langle \partial_t u, u \rangle = \langle Lu, u \rangle - \langle B(u, u), u \rangle + \langle f, u \rangle$$

$$\leq -\|u\|_{H^1}^2 + \|u\|_{H^1} \|f\|_{H^{-1}}$$

$$\leq -\frac{1}{2} \|u\|_{H^1}^2 + \frac{1}{2} \|f\|_{H^{-1}}^2$$

$$\Rightarrow \|u(t)\|_{L^2}^2 + \int_0^t \|u(t')\|_{H^1}^2 dt' \leq \|u_0\|_{L^2}^2 + \int_0^t \|f(t')\|_{H^{-1}}^2 dt'$$

( $\Rightarrow \sup$  in  $t \in [0, T]$ )

Remark:

$$\|u(t)\|_{L^2}^2 + 2 \int_0^t \|\nabla u(t')\|_{L^2}^2 dt' = \|u(0)\|_{L^2}^2 + 2 \int_0^t \langle f(t'), u(t') \rangle dt'$$

$$\Rightarrow \|u\|_{L_T^\infty L_x^2} + \|u\|_{L_T^2 H_x^1} \leq c(u_0, f)$$

By (B2),

$$\|B(u)\|_{H^{-1}} \lesssim \|u\|_{H^{1/2}}^2 \lesssim \|u\|_{L^2} \|u\|_{H^1}$$

$$\|\partial_t u\|_{L_T^2 H_x^{-1}} \stackrel{(NSE)}{\leq} \|Lu\|_{L_T^2 H_x^{-1}} + \|u\|_{L_T^\infty L_x^2} \|u\|_{L_T^2 H_x^1} + \|f\|_{L_T^2 H_x^{-1}}$$

$$\leq c(u_0, f) = c(\|u_0\|_{L^2}, \|f\|_{L_T^2 H_x^{-1}}) \leftarrow \text{non-decreasing function.}$$

$$\Rightarrow \|u\|_{X_T} \leq c(u_0, f)$$

Step 2: Galerkin approximation

Define  $p_N: L_{df}^2 \rightarrow E_N = \text{span}\{e_n: |n| \leq N\}$ .

Apply  $p_N$  to the equation

$$\partial_t p_N u - L p_N u + p_N B(u) = p_N f$$

$$u_N = p_N u$$

$$(NSE_N) \begin{cases} \partial_t u_N - L u_N + p_N B(u_N) = p_N f \\ u_N|_{t=0} = p_N u_0 \end{cases}$$

finite dimensional system of ODEs on the "Fourier" side.

## Euler equation

$$\partial_t u + u \cdot \nabla u + \nabla p = 0$$

energy:  $\frac{1}{2} \int |u|^2 dx$  is conserved if  $u \in C^{1/3}$

$\hookrightarrow$  Onsager's conjecture

$\sim 2010$ , De Lellis, Scirehidi

- convex integration,  $\exists$  wild solutions
- $L^\infty, C^0$  non-uniqueness given  $e(t): \mathbb{R}_+ \rightarrow \mathbb{R}_+$
- $\exists u$  s.t.  $e(t) = \frac{1}{2} \int |u(t)|^2 dx$

• Isett:  $C^\alpha, \alpha < \frac{1}{10}, \frac{1}{5}$

$\hookrightarrow C^{1/3}$

• Buckmaster

• Vicol

By Cauchy-Lipschitz theorem,  $\exists!$  local-in-time solution  $u_N$ .

→ blowup alternative:

$u_N$  exists on  $[0, \tau]$

OR

$$\exists T_N < \tau \text{ s.t. } \lim_{t \rightarrow T_N^-} \|u_N(t)\|_{L^2} = \infty.$$

Multiply (NSE<sub>N</sub>) by  $u_N$  and integrate

$$\Rightarrow \sup_{N \geq 1} (\|u_N\|_{X_T} + \|u_N\|_{L_T^\infty L_x^2}) \leq C(u_0, f)$$

$$\langle P_N B(u_N), u_N \rangle$$

"  
 $\langle B(u_N), u_N \rangle$   
 and same computations hold.

•  $u_N$  exists on  $[0, \tau]$

•  $u_{N_j} \rightarrow u$  in  $X_T$

$$\partial_t u_{N_j} \rightarrow \partial_t u$$

$$L u_{N_j} \rightarrow L u \quad \text{in } L_T^2 H_x^{-1}$$

By Aubin-Lions, compactness Lemma,  $\exists$  subsequence  $u_{N_j}$

$$u_{N_j} \rightarrow u \quad \text{in } L_T^2 H_x^{1/2}$$

(B2)

$$\Rightarrow B(u_{N_j}) \rightarrow B(u) \quad \text{in } L_T^1 H_x^{-1}$$

By definition of  $P_{N_j}$ :

$$u_{N_j}(0) = P_{N_j} u_0 \rightarrow u_0 \quad \text{in } L_x^2.$$

$$P_{N_j} f \rightarrow f \quad \text{in } L_T^2 H_x^{-1}$$

$$(NSE_{N_j}) \quad \partial_t u_{N_j} - L u_{N_j} + \underbrace{P_{N_j} B(u_{N_j})}_{\text{problematic}} = P_{N_j} f$$

↪ Apply  $P_m$  for fixed  $m$ , then  $N_j \geq m$  (which holds for  $j \gg 1$ )

$$\partial_t P_m u_{N_j} - L P_m u_{N_j} + P_m B(u_{N_j}) = P_m f$$

$$j \rightarrow \infty \quad \downarrow \quad \text{in } L_T^1 H_x^{-1}$$

$$(*) \quad \partial_t P_m u - L P_m u + P_m B(u) = P_m f$$

(\*) holds for any  $m \geq 1 \Rightarrow$  Take  $m \rightarrow \infty$

$$\begin{cases} \partial_t u - L u + B(u) = f \\ u|_{t=0} = u_0 \quad \text{in } L^2 \end{cases}$$

Remark:

We can also start with a given subsequence  $u_{N_j}$   $\Rightarrow$  show  $\exists$  subseq. of subseq.  $\rightarrow u$

$\Rightarrow u_N$  converges to  $u$

entire sequence

independent of  
 choice of  
 subseq.  $u_{N_j}$

• Energy bound: By weak convergence

$$\|u\|_{L_T^2 H_x^1} \leq \liminf_{j \rightarrow \infty} \|u_{N_j}\|_{L_T^2 H_x^1}$$

& definition of  $P_{N_j}$ .

weak \* convergence

$$\|u(t)\|_{L_T^\infty L_x^2} \leq \liminf \|u_{N_j}\|_{L_T^\infty L_x^2}$$