The Convex Magnitude Conjecture

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with



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These slides: available on my web page

Executive summary

Magnitude is a real-valued invariant of metric spaces.

It seems not to have been previously investigated.

Conjecturally, it captures a great deal of geometric information.

It arose from a general study of 'size' in mathematics.

1. Where does magnitude come from?

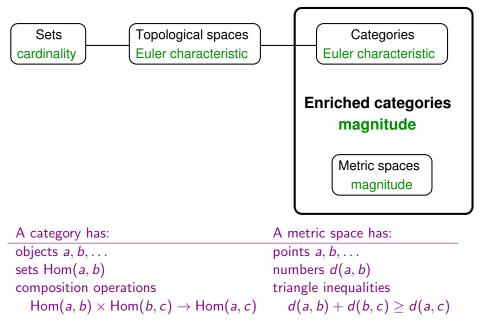
2. The magnitude of a finite space

3. The magnitude of a compact space

4. The convex magnitude conjecture

1. Where does magnitude come from?

Concepts of counting and size



2. The magnitude of a finite space

The definition

Let $A = \{a_1, \ldots, a_n\}$ be a finite metric space.

Write Z or Z_A for the $n \times n$ matrix given by $Z_{ij} = e^{-d(a_i, a_j)}$.

A weighting on A is a column vector $w \in \mathbb{R}^n$ such that

$$Zw = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$$
.

Suppose there is at least one weighting w on A. The magnitude of A is

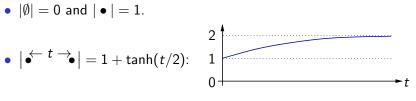
$$|A| = \sum_j w_j \in \mathbb{R}.$$

This is independent of the weighting chosen.

E.g.: Usually Z is invertible. Then A has magnitude

$$|A|=\sum_{i,j}(Z^{-1})_{ij}.$$

Examples



• If $d(a_i, a_j) = \infty$ for all $i \neq j$ then $|\{a_1, \dots, a_n\}| = n$.

Digression: magnitude as maximum diversity Take a probability distribution p on a finite metric space $A = \{a_1, \ldots, a_n\}$. Its entropy (of order 1) is

$$H_A(p) = -\sum_{i=1}^n p_i \log(Z_A p)_i$$

Ecological interpretation:

- points of A represent species
- distances represent differences between species
- probabilities represent frequencies
- exponential of entropy measures biological diversity.

Given a list of species, which distribution maximizes diversity?

Theorem: Under hypotheses,

- the maximizing distribution p is the weighting w, normalized
- the maximum diversity is the magnitude: max $e^{H_A(p)} = |A|$.

Magnitude functions

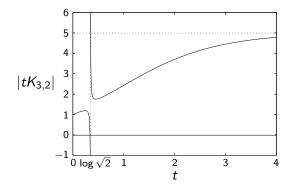
Magnitude changes unpredictably as a space is rescaled.

For a space A and t > 0, let tA be A scaled up by a factor of t.

The magnitude function of A is the function $t \mapsto |tA|$ on $(0, \infty)$. (It may have a finite number of singularities.)

E.g.: The magnitude function of $\bullet \stackrel{\leftarrow}{\leftarrow} 1 \rightarrow \bullet$ is $t \mapsto 1 + \tanh(t/2)$.

E.g.: Magnitude functions can be wild for small *t*, but behave well for large *t*:



Positive definite spaces

A (possibly infinite) metric space A is positive definite if for each finite $B \subseteq A$, the matrix Z_B is positive definite.

Examples of positive definite spaces:

- Euclidean space \mathbb{R}^N
- the sphere S^N with the geodesic metric.

For finite positive definite spaces, magnitude behaves intuitively, e.g.:

- the magnitude is always defined
- $|A| \ge 1$ for nonempty A
- if $B \subseteq A$ then $|B| \leq |A|$.

3. The magnitude of a compact space

Extending the definition beyond finite spaces

How could we define the magnitude of an *infinite* space?

- Idea: approximate it by finite spaces.
- Alternative idea: replace sums by integrals. (Then weightings become measures or distributions.)

Meckes has shown: for compact, positive definite spaces, both ideas work. Moreover, they give the same answer.

The definition

Theorem (Meckes)

Let A be a positive definite compact metric space (e.g. $A \subseteq \mathbb{R}^N$).

Let $B_1 \subseteq B_2 \subseteq \cdots \subseteq A$ be finite subspaces with $\overline{\bigcup B_i} = A$.

Then $\lim_{i\to\infty} |B_i|$ exists and depends only on A (not on the sequence (B_i)).

The magnitude |A| of A is defined as $\lim_{i \to \infty} |B_i|$.

Digression: Meckes has also shown:

$$|A| = \sup\left\{\frac{\mu(A)^2}{\int_A \int_A e^{-d(x,y)} d\mu(x) d\mu(y)} \,\middle|\, \text{signed Borel measures } \mu \text{ on } A\right\}.$$

Examples

- $|[0, t]| = 1 + \frac{1}{2}t.$
- For $A = [0, p] \times [0, q]$ with the ℓ^1 (taxicab) metric,

$$egin{aligned} |A| &= (1+rac{1}{2}p)(1+rac{1}{2}q) \ &= 1+rac{1}{4} \, { extsf{perimeter}}(A) + rac{1}{4} \, { extsf{area}}(A). \end{aligned}$$

So the magnitude function of A is

$$t\mapsto \left| \left| tA
ight| = 1 + rac{1}{4} \operatorname{perimeter}(A) \cdot t + rac{1}{4} \operatorname{area}(A) \cdot t^2
ight|$$

(a polynomial of degree 2).

Magnitude dimension

Let A be a compact positive definite metric space (e.g. $A \subseteq \mathbb{R}^N$). The magnitude dimension of A is

$$\dim_{\mathsf{mag}} A = \inf \Big\{ r \ge 0 : \frac{|tA|}{t^r} \text{ is bounded for } t \gg 0 \Big\}.$$

Examples:

- Finite sets have magnitude dimension 0.
- Line segments have magnitude dimension 1.
- The Cantor set has magnitude dimension log₃ 2.
- The *N*-sphere with geodesic metric has magnitude dimension *N*.

Theorem (with Meckes): For compact $A \subseteq \mathbb{R}^N$,

$$\dim_{\text{Hausdorff}}(A) \leq \dim_{\text{mag}}(A) \leq N.$$

(But magnitude dimension and Hausdorff dimension sometimes disagree.)

4. The Convex Magnitude Conjecture

The conjecture (in 2 dimensions)

Recall that for rectangles A in \mathbb{R}^2 with the ℓ^1 metric,

$$|A| = 1 + \frac{1}{4}$$
 perimeter $(A) + \frac{1}{4}$ area (A) .

Conjecture (with Willerton)

For compact convex $A \subseteq \mathbb{R}^2$ (with the Euclidean metric),

$$|A| = \chi(A) + \frac{1}{4}$$
 perimeter $(A) + \frac{1}{2\pi}$ area (A) .

Equivalently: for compact convex $A \subseteq \mathbb{R}^2$ and t > 0,

$$|tA| = \chi(A) + rac{1}{4}$$
 perimeter $(A) \cdot t + rac{1}{2\pi}$ area $(A) \cdot t^2.$

In particular: the magnitude function of a convex planar set is a polynomial, from which we can recover its Euler characteristic, perimeter and area.

The conjecture (in arbitrary dimension)

Let ω_i denote the volume of the *i*-dimensional unit ball.

Let V_i denote *i*-dimensional intrinsic volume.

Conjecture (with Willerton)

For compact convex $A \subseteq \mathbb{R}^N$ (with the Euclidean metric),

$$|A| = \sum_{i=0}^{N} \frac{1}{i!\omega_i} V_i(A).$$

Equivalently: for compact convex $A \subseteq \mathbb{R}^N$ and t > 0,

$$|tA| = \sum_{i=0}^{N} \frac{1}{i!\omega_i} V_i(A) \cdot t^i.$$

In particular: the magnitude function of a convex set in \mathbb{R}^N is a polynomial, from which we can recover all of its intrinsic volumes.

A gap

- There is not a single example for which the conjecture is known to be true, apart from line segments.
- That is: apart from line segments, there is no compact convex set whose magnitude is known.
- E.g. the magnitude of the unit disk is unknown.

(Nor is there is a single example for which it is known to be false.)

Evidence for the conjecture, I

Recall: the conjecture states that for compact convex $A \subseteq \mathbb{R}^2$,

$$|tA| = \chi(A) + rac{1}{4}$$
 perimeter $(A) \cdot t + rac{1}{2\pi}$ area $(A) \cdot t^2.$

- The conjecture holds when A is a line segment.
- Both sides are monotone in A.
- Both sides have the same growth as $t \to \infty$.
- $|tA| \ge \chi(A)$ and $|tA| \ge \frac{1}{2\pi} \operatorname{area}(A) \cdot t^2$.
- Numerical (Willerton): computer calculations for disk, square, etc.
- Heuristic argument (Willerton) for why the top coefficient should be $\frac{1}{2\pi}$.

Evidence, II: arguments by analogy

Recall: the conjecture states that for compact convex $A \subseteq \mathbb{R}^2$,

$$|tA| = \chi(A) + rac{1}{4}$$
 perimeter $(A) \cdot t + rac{1}{2\pi}$ area $(A) \cdot t^2$.

Theorem: For compact convex $A \subseteq \mathbb{R}^2$ with the ℓ^1 metric,

$$|tA| = \chi(A) + \frac{1}{2} \Big[\mathsf{length}(\pi_1 A) + \mathsf{length}(\pi_2 A) \Big] \cdot t + \frac{1}{4} \operatorname{area}(A) \cdot t^2.$$

Theorem (Willerton): For homogeneous Riemannian 2-manifolds A,

$$|t \mathsf{A}| = O(t^{-2}) + \chi(\mathsf{A}) + rac{1}{2\pi} \operatorname{area}(\mathsf{A}) \cdot t^2$$

as $t \to \infty$.

Evidence, III: PDE approach

Recall: the conjecture states that for compact convex $A \subseteq \mathbb{R}^2$,

$$|tA| = \chi(A) + \frac{1}{4}$$
 perimeter $(A) \cdot t + \frac{1}{2\pi}$ area $(A) \cdot t^2$.

Juan Antonio Barcelo and Tony Carbery (following Meckes) have a PDE approach, best adapted to magnitude of convex sets in odd dimensions.

For compact convex $A \subseteq \mathbb{R}^3$, they define a quantity [A] in terms of the solution to a certain PDE.

- A nonrigorous argument suggests that [A] = |A|.
- A *rigorous* argument shows that when A is the ball, [A] is exactly what the convex magnitude conjecture predicts.

Similar arguments probably work for the N-ball whenever N is odd.

How could we prove the conjecture?

Recall: the conjecture states that for compact convex $A \subseteq \mathbb{R}^2$,

$$|tA| = \chi(A) + rac{1}{4}$$
 perimeter $(A) \cdot t + rac{1}{2\pi}$ area $(A) \cdot t^2.$

If the conjecture holds then magnitude is a convex valuation:

$$|A \cup B| = |A| + |B| - |A \cap B|$$
 for all convex $A, B, A \cup B$.

Almost-conversely, by Hadwiger's theorem, the conjecture holds as long as:

- magnitude is a convex valuation, and
- the conjecture holds for at least one 2-dimensional set.

But currently, no one knows how to do either step.

What's the point?

- It's hard.
- If the conjecture is true, it exhibits the intrinsic volumes of convex sets as intrinsic metric invariants — independent of their embedding in R^N. (Compare the Weyl tube formula.)
- It suggests an approach to geometric measure that works for spaces that are irregular, or not embedded in any standard space such as R^N.
- The categorical origins suggest that magnitude is a canonical quantity of mathematics: a cousin of cardinality and Euler characteristic, and therefore worth studying.

The conjecture, in one slide

For
$$B = \{b_1, \dots, b_n\} \subseteq \mathbb{R}^N$$
, define $Z_{ij} = e^{-d(b_i, b_j)}$ and $|B| = \sum_{i,j} (Z^{-1})_{ij}$.

For compact $A \subseteq \mathbb{R}^N$, choose finite sets $B_1 \subseteq B_2 \subseteq \cdots \subseteq A$ with $\overline{\bigcup B_i} = A$, then define $|A| = \lim_{i \to \infty} |B_i|$.

Conjecture (2-dimensional case): For compact convex $A \subseteq \mathbb{R}^2$,

$$|A| = \chi(A) + \frac{1}{4}$$
 perimeter $(A) + \frac{1}{2\pi}$ area (A) .

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