

Classical mechanics

M configuration space

$L: TM \rightarrow \mathbb{R}$ Lagrangian

$\gamma: [t_0, t_1] \rightarrow M$

$\gamma(t_0) = x_0 \quad \gamma(t_1) = x_1$

Principle of least action:

$$S(\gamma) = \int_{t_0}^{t_1} L(\gamma, \dot{\gamma}) dt$$

γ is a physical path if local minimum for S .

E.g. g a metric on M

$$L(x, v) = g_x(v, v)$$

Euler-Lagrange equations; for a physical path:

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} = \frac{\partial L}{\partial q}$$

E.g. geodesic flow on $TS^1 = S^1 \times \mathbb{R}$
 (θ, λ)

$$L: S^1 \times \mathbb{R} \rightarrow \mathbb{R}$$

$$(\theta, \lambda) \mapsto \lambda^2$$

$$\frac{\partial L}{\partial \lambda} = 2\lambda$$

$$\frac{d}{dt} (2\lambda(t)) = 0$$

Hamiltonian formulation:

$$\Phi: TM \rightarrow T^*M$$

$$\begin{array}{c} v \\ \downarrow \\ m \\ T_q M \end{array} \mapsto d(L|_{T_q M})_v \in T_v^*(T_q M) \cong (T_q M)^*$$

Assume Φ is a diffeomorphism

$$H: T^*M \rightarrow \mathbb{R}$$

$$H(p) := dL_{\Phi^{-1}(p)}(\Phi^{-1}(p)) - L(\Phi^{-1}(p))$$

E.g. Hamiltonian mechanics

T = kinetic energy

V = pot. energy

$$L = \frac{1}{2}(T - V)$$

$$H = T - L = \frac{1}{2}(T + V)$$

$$q = \frac{\partial H}{\partial p} \quad p = -\frac{\partial H}{\partial q}$$

Now given T^*M , we define a canonical 1-form λ :

$$\lambda_{(q,p)} = -\pi^* p$$

$$= -\sum_i p_i dq^i$$

symplectic form $d\lambda = \sum_i dq^i \wedge dp_i$

Hamiltonian differential equation:

$$\text{given } H: T^*M \rightarrow \mathbb{R}$$

$$\mathcal{L}_{X_H} \omega = dH \quad \text{defines } X_H - \text{Hamiltonian vector field}$$

the diff. eqn. is the flow of X_H .

Lagrangian submanifolds:

- the zero section $M \subset T^*M$
- the graph of a closed 1-form
- the graph of an exact 1-form is an exact Lagrangian.
(i.e. $\lambda|_L$ is exact)
- Given a submanifold $N \hookrightarrow M$, there is an exact Lagrangian $T_N^*M \subset T^*M$ (the conormal of N)

$$T_N^*M = \left\{ (q, p) \in T^*M : q \in N, p|_{T_q N} = 0 \right\}$$

In local coordinates, if $N = (q_1, \dots, q_k, 0, \dots, 0)$

$$T_N^* M = (q_1, \dots, q_k, 0, \dots, 0, 0, \dots, 0, p_{k+1}, \dots, p_m)$$

Hybrid Lagrangian

$$\alpha \in \Omega^1(N)$$

$$T_{N,d}^* M = T_N^* M + \alpha = \{(q, p) \in T^* M : p|_{T_q N} = \alpha\}$$

$T_{N,d}^* M$ is Lagrangian $\Leftrightarrow \alpha$ is a closed form on N

" " exact " \Leftrightarrow " " exact " " "

Exact symplectic manifold

$$(M, \omega, \lambda)$$

$$d\lambda = \omega$$

$$\mathcal{L}_Z \omega = \lambda \quad Z = \text{Liouville vector field}$$

$\mathcal{L}_Z \omega = \omega \Rightarrow Z$ expands the symplectic form.

$$\text{E.g. on } T^* M, Z = \sum p_i \frac{\partial}{\partial p_i}$$

Defn: contracting vector field: $\mathcal{L}_Z \omega = c(x)\omega \quad c(x) < 0$

($\Rightarrow \exists$ a primitive)

Defn: Weinstein mfd: (M, ω, Z, h)

where h is an exhausting Morse function

Z is contracting and complete

gradient-like: $dh(Z) > 0$ away from critical points

$Z = \nabla h$ near critical points

h has finitely many critical points.