

Mathematical Techniques III (PHY 317)

Problem Set 1

Due on Monday, October 5th by 6pm

Problem 1. (10 points)

Let $\mathbb{R}^N = \{(v_1, v_2, \dots, v_N) \mid v_i \in \mathbb{R}\}$ be the set of N -tuples of real numbers. Show that \mathbb{R}^N is a vector space with respect to the following operations:

(addition)

$$\begin{aligned} (v_1, v_2, \dots, v_N) + (w_1, w_2, \dots, w_N) \\ = (v_1 + w_1, v_2 + w_2, \dots, v_N + w_N), \end{aligned}$$

(multiplication by scalars)

$$\lambda (v_1, v_2, \dots, v_N) = (\lambda v_1, \lambda v_2, \dots, \lambda v_N) \quad \text{for } \lambda \in \mathbb{R}.$$

Determine which of the following subsets of \mathbb{R}^N are vector subspaces:

1. The subset $\{(v_1, v_2, \dots, v_N) \mid v_1 + v_2 + \dots + v_N = 0\}$,
2. The subset $\{(v_1, v_2, \dots, v_N) \mid v_1 + v_2 + \dots + v_N = 1\}$, and
3. The subset $\{(v_1, v_2, \dots, v_N) \mid v_i \in \mathbb{Q}\}$, where \mathbb{Q} denotes the rational numbers.

Problem 2. (10 points)

Show that the set \mathcal{F} consisting of real-valued functions on the interval $[-1, 1]$,

$$\begin{aligned} f : [-1, 1] &\rightarrow \mathbb{R} \\ t &\mapsto f(t), \end{aligned}$$

is a vector space under the following operations:

$$(f + g)(t) = f(t) + g(t) \quad \text{(addition)}$$

$$(\lambda f)(t) = \lambda f(t) \quad \text{(multiplication by scalars)}$$

for $f, g \in \mathcal{F}$ and $\lambda \in \mathbb{R}$.

Determine which of the following subsets of \mathcal{F} are vector subspaces:

1. The subset $\{f \in \mathcal{F} \mid f(0) = 0\}$,
2. The subset $\{f \in \mathcal{F} \mid f(0) = 1\}$,
3. The subset $\{f \in \mathcal{F} \mid f(-1) = f(1)\}$, and
4. The subset consisting of functions which satisfy the differential equation

$$f'' + 2f' - 5f = 0 ,$$

where the prime indicates derivative with respect to t .

Problem 3. (15 points)

Show that the rotation R_θ in the plane through an angle θ about the origin is a linear transformation. Show that the matrix \mathbf{R}_θ representing R_θ with respect to the canonical basis is given by

$$\mathbf{R}_\theta = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} ,$$

and compute its determinant. Prove in addition that $\mathbf{R}_\theta \mathbf{R}_\phi = \mathbf{R}_{\theta+\phi}$ and $\mathbf{R}_\theta^{-1} = \mathbf{R}_{-\theta}$.

(These properties make the matrices $\{\mathbf{R}_\theta \mid 0 \leq \theta < 2\pi\}$ into a **group**, called $\text{SO}(2)$.)

Show that the reflection F of the plane in the x -axis is linear. Show that the matrix \mathbf{F} which represents F with respect to the canonical basis is given by

$$\mathbf{F} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} ,$$

and compute its inverse and its determinant. Prove that $\mathbf{F} \mathbf{R}_\theta = \mathbf{R}_\theta^{-1} \mathbf{F}$.

Problem 4. (15 points)

For each of the following matrices:

$$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}, \quad \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix},$$

$$\begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad \begin{pmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{pmatrix}, \quad \text{and} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix},$$

1. calculate its determinant,
2. describe its action on the canonical basis of \mathbb{R}^2 (for 2×2 matrices) or \mathbb{R}^3 (for 3×3 matrices), and
3. give a geometrical interpretation of the corresponding linear transformation.