

Solutions for Exercises for Lectures 2 & 3.

1. Let $X = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$. Then $X^2 = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$ and $X^3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Now $\rho(x^i) = X^i \quad 0 \leq i \leq 2$ and we get

$$\begin{aligned} \rho(x^i \cdot x^j) &= \rho(x^{i+j}) = \rho(x^k) && (k \in i+j \text{ } (3) \\ &&& 0 \leq k \leq 2) \\ &= X^k \\ &= X^i X^j && (\text{since } X^3 = \text{Id}) \\ &= \rho(x^i) \rho(x^j) \end{aligned}$$

so it's a group homomorphism i.e. a rep⁺.

2. $e_1 + e_2 + e_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ is fixed by these matrices
 i.e. $X \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \therefore X^i \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

$\therefore \mathbb{C} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ is a 1-D subrep⁺.

Now the answer on whether there are more 1-D reps depends on which field we work over:

Suppose $\mathbb{F}v$ is stable under X (and hence X^i).

Then $Xv = \lambda v$ for some $\lambda \in \mathbb{F}$ i.e. v is an \mathbb{F} -vector and λ an \mathbb{F} -value.

$$\begin{aligned} \det(tI - X) &= \begin{vmatrix} t & -1 & 0 \\ 0 & t & -1 \\ -1 & 0 & t \end{vmatrix} = t(t^2) + 1(-1) + 0 \\ &= t^3 - 1 \\ &= (t-1)(t^2 + t + 1) \end{aligned}$$

Now we have the \mathbb{F} -value 1 and we found $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ to be

an e-vector. Now the existence of other e-vectors depends on whether t^2+t+1 factorises over \mathbb{F}

e.g. it doesn't factorise over \mathbb{R} ad so there are no other 1-D subrep's.

e.g. over \mathbb{C} $t^2+t+1 = (t-\omega)(t-\omega^2)$ where $\omega = \exp\left(\frac{2\pi i}{3}\right)$
ad so there are 2 more 1-D reps spanned by $\begin{pmatrix} 1 \\ \omega \end{pmatrix}$ and $\begin{pmatrix} 1 \\ \omega^2 \end{pmatrix}$ respectively.

$$\begin{aligned} 3. \quad g_j(x^m x^{n'}) &= g_j(x^{m+n'}) = g_j(x^k) \quad (\text{where } k = m+n'(n)) \\ &= p_{jk} \\ &= p_j(m+n') \quad \text{since } p^n = 1 \\ &= g_j(x^m) g_j(x^{n'}) \end{aligned}$$

So we get a repⁿ.

Obviously $g_j \cong p_{tn+j}$ $\forall t \in \mathbb{Z}$ since $p_{tn+j} = p_j$.

Now we claim that g_0, \dots, g_{n-1} are all non-isomorphic.

This is easy : suppose $\psi: \mathbb{C} \rightarrow \mathbb{C}$ is an isom. between g_i ad g_j . Then we have $\forall \lambda$

$$\psi(g_i(x^m) \cdot \lambda) = g_j(x^m) \cdot \psi(\lambda) \quad \forall \lambda \in \mathbb{C}.$$

$$\psi(p_i^{jm} \lambda) = p_j^{jm} \psi(\lambda)$$

$$p_i^{jm} \psi(\lambda) \quad (\text{by } \mathbb{C}\text{-linearity})$$

Thus if $\psi(\lambda) \neq 0$ we get $p^{im} = p^{jm} \quad \forall m$

so that $y^i = y^j$ i.e. $i=j$ (since $0 \leq i, j \leq n-1$)

& This is a contradiction, so $\psi(\lambda) = 0 \quad \forall \lambda \in C$ and so $\psi = 0$ i.e. ψ is not invertible, i.e. ψ is not an homom.

(4). We have to check that ρ^* is a group homomorphism.

$$\begin{aligned}\rho^*(g_1 g_2) &= \rho((g_1 g_2)^{-1})^T = \rho(g_2^{-1} g_1^{-1})^T \\ &\stackrel{\rho \text{ is a homom.}}{=} (\rho(g_2^{-1}) \rho(g_1^{-1}))^T \\ &= \rho(g_1^{-1})^T \rho(g_2^{-1})^T \\ &= \rho^*(g_1) \rho^*(g_2).\end{aligned}$$

Thus ρ^* is a repⁿ, and it has the same degree as ρ as it consists of matrices of the same size.

$$(5) \quad \rho^*(x) = \rho(x^{-1})^T = \rho(x^2)^T = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} = \rho(x), \text{ so}$$

the repⁿs are the same.

$$\begin{aligned}\text{For } q_{n,2}: \quad \rho_j^*(x^k) &= \rho_j(x^{n-k})^T = p_j^{(n-k)} \cdot \cancel{\rho_j} \\ &= p_j^{(n-j)k} \quad (\text{since } p^n = 1) \\ &= \rho_{n-j}^*(x^k)\end{aligned}$$

$$\text{So } \rho_j^* \cong \rho_{n-j}.$$

$$(6) \quad (a) \quad F[X] \text{ has a basis } (e_x : x \in X) \text{ where } e_x \in F[X]$$

in the function $e_x(y) = \delta_{xy} = \begin{cases} 1 & y=x \\ 0 & y \neq x \end{cases}$

To see this : (i) $f \in F[X]$, then $f = \sum_{x \in X} f(x) e_x$

since ~~$\forall y \in X$~~ $(\sum_{x \in X} f(x) e_x)(y) = \sum_{x \in X} f(x) e_x(y)$
 $= f(y)$

Thus $(e_x : x \in X)$ spans.

(ii) Suppose that $\sum_{x \in X} \lambda_x e_x = 0$ $\lambda_x \in F$ for

then $0 = (\sum_{x \in X} \lambda_x e_x)(y) = \sum_{x \in X} \lambda_x e_x(y) = \lambda_y \quad \forall y \in X$

i.e. $(e_x : x \in X)$ linearly independent set.

(b) We need to check that $g \mapsto g \circ f$ is a linear mapping

i.e. $g \cdot (\lambda_1 f_1 + \lambda_2 f_2) = \lambda_1 (g \cdot f_1) + \lambda_2 (g \cdot f_2) \quad \forall \lambda_1, \lambda_2 \in F$
 $f_1, f_2 \in F[C]$

Well let $x \in X$

$$\begin{aligned} (g \cdot (\lambda_1 f_1 + \lambda_2 f_2))(x) &= (\lambda_1 f_1 + \lambda_2 f_2)(g^{-1}x) \\ &= \lambda_1 (f_1(g^{-1}x)) + \lambda_2 (f_2(g^{-1}x)) \\ &= \lambda_1 ((g \cdot f_1)(x)) + \lambda_2 (g \cdot f_2)(x)) \\ &= (\lambda_1 (g \cdot f_1) + \lambda_2 (g \cdot f_2))(x) \end{aligned}$$

so the maps are equal!

(c) We need to show that

$$\begin{aligned} \varrho: G &\longrightarrow \cancel{GL}(V) & V = F[X] \\ g &\longmapsto (f \mapsto g \cdot f) & f \in V \end{aligned}$$

is a group homomorphism:

$(f \mapsto g \cdot f)$ belongs to $GL(V)$ since its inverse is $f \mapsto g^{-1} \cdot f$

$$\varrho(gh)(f) = (gh) \cdot f \quad \varrho(g)\varrho(h)(f) = g \cdot (h \cdot f)$$

i.e. we must show that $(gh) \cdot f = g \cdot (h \cdot f)$

$$\text{let } x \in X \quad ((gh) \cdot f)(x) = f((gh)^{-1}x)$$

$$\begin{aligned} &= f((h^{-1}g^{-1})x) \quad \text{G action on } X. \\ &= f(h^{-1}(g^{-1}x)) \end{aligned}$$

$$= (h \cdot f)(g^{-1}x)$$

$$= (g \cdot (h \cdot f))(x).$$

(d) It's not irreducible unless X is a single element, because

$$f = \sum_{x \in X} e_x \quad \text{is fixed by } G : (g \cdot f)(x) = \sum_{x \in X} g \cdot e_x$$

$$\begin{aligned} \text{we use } (g \cdot e_x)(y) &= e_x(g^{-1}y) = \begin{cases} 1 & x = g^{-1}y \\ 0 & x \neq g^{-1}y \end{cases} & \stackrel{(*)}{=} \sum_{x \in X} e_{g^{-1}x} \\ &= \begin{cases} 1 & gx = y \\ 0 & gx \neq y \end{cases} = e_{gx}(y) & = \sum_{x \in X} e_x = f \end{aligned}$$

So Fg is a 1-D subrepⁿ.

(7) (a) To start with we have arbitrary words of the form
 $a^{i_1} b^{i_2} a^{i_3} b^{i_4} \dots$

but we notice that, & the relation $bab^{-1} = a^3$ can be rewritten $bab^{-1} = a^3$ and then $ba = a^3b$. This allows to ~~swap~~ move b's from the left to the right
 i.e. $ba^2 = \underline{ba}a = a^3\underline{ba} = a^3a^3b$

So all elements of D_g can actually be written as

$$a^i b^j \quad i, j \in \mathbb{Z}.$$

Now we can choose $0 \leq i \leq 3$, $0 \leq j \leq 1$ since $a^4 = b^2 = e$
 so we can write every element in the form

$$a^i b^j \quad \text{with } 0 \leq i \leq 3, 0 \leq j \leq 1.$$

(b) (we haven't actually proved that the 8 elements are all different in $\langle a, b : a^4 = b^2 = e, bab^{-1} = a^3 \rangle$;
 that will follow from Q.11 — at the moment we'll just assume it)

$$e, \{a, a^3\}, \{a^2\}, \{b, a^2b\}, \{ab, a^3b\}.$$

(by calculation)

e.g. $\{a, a^3\}$ are conjugate because of the relation
 $bab^{-1} = a^3$

e.g. ab, a^3b are conjugate since $b(ab)b^{-1} = ba = a^3b$,

(8)(a) Exactly the same argument as 7(a) gives every element in $\{a^i b^j : 0 \leq i \leq n-1, 0 \leq j \leq 1\}$.

(b) The same arguments give: n even

$$\text{sets, } \{a^n\}, \left\{ a^i, a^{n-i} \right\}_{\substack{1 \leq i < \frac{n}{2}}} \quad \begin{cases} \{b, a^2b, a^4b, \dots, a^{n-2}b\} \\ \{ab, a^3b, a^5b, \dots, a^{n-1}b\} \end{cases}$$

$$n \text{ odd } \{e\}, \left\{ a^i, a^{n-i} \right\}_{\substack{1 \leq i < \frac{n}{2}}}, \{b, ab, a^2b, \dots, a^{n-1}b\}.$$

(9) (a) e, a, b, ab, ba, aba . (Can you convince yourself these are really different? See Q.14)

(b) $a = (12), b = (23)$. Then

$$(12)^2 = (23)^2 = e \quad (12)(23)(12) \quad (23)(12)(23) \\ " \quad " \quad (23) = (13).$$

(10) Write $s_\alpha(x_1, \dots, x_r)$ as some word $x_1^{i_1} \dots x_r^{i_r} x_1^{j_1} \dots x_r^{j_r} \dots$

$$\begin{aligned} \text{Then } g(s_\alpha(x_1, \dots, x_r)) &= g(x_1^{i_1} \dots x_r^{i_r} x_1^{j_1} \dots x_r^{j_r} \dots) \\ &= g(x_1)^{i_1} \dots g(x_r)^{i_r} g(x_1)^{j_1} \dots g(x_r)^{j_r} \dots \quad \text{by defn} \\ &= x_1^{i_1} \dots x_r^{i_r} x_1^{j_1} \dots x_r^{j_r} \dots \\ &= s_\alpha(X_1, \dots, X_r) \end{aligned}$$

$$\therefore g(s_\alpha(x_1, \dots, x_r)) = e_H \Leftrightarrow s_\alpha(X_1, \dots, X_r) = e_H$$

(11) We need to check that $g(a^4) = \text{Id}_2 = g(b^2)$ and that $g(bab^{-1}) = g(a^{-1})$; then it follows from the analysis preceding Q.10 that we have a homomorphism from $\langle a, b : a^4 = b^2 = e, bab^{-1} = a^{-1} \rangle$ to $\text{GL}_2(F)$ i.e a rep n .

$$g(a^4) = g(a)^4 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^4 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad (\text{by calculation})$$

$$g(b^2) = g(b)^2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \text{ obviously}$$

$$g(bab^{-1}) = g(b)g(a)g(b)^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = g(a)^3$$

$$= g(a)^{-1}$$

$$= g(a^{-1})$$

(11) (Aside: this also proves that ~~each of~~ the elements $a^i b^j$ ($0 \leq i \leq 3$, $0 \leq j \leq 1$) are all distinct since they are all sent to different matrices — that fully finishes off (7).)

(12) Here's 2.7 : $a^i \xrightarrow{\sigma} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}^i$, $b^j \xrightarrow{\sigma} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^j$

We need to check that $a^3 = b^2 = e$, $bab^{-1} = a^{-1}$ are satisfied by these matrices: the relations

$$\sigma(a^3) = \sigma(a)^3 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}^3 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \sigma(b^2) = \sigma(b)^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\sigma(bab^{-1}) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix}^{-1} = \sigma(a^{-1})$$

so we do get a repⁿ.

Here's 2.4' : $a \xrightarrow{\sigma'} \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}$, $b \xrightarrow{\sigma'} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$

Again, we have to check the relations:

$$\begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}^3 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad (\text{because the matrix represents rot}^n \text{ by } 2\pi/3)$$

$$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{pmatrix} = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}^{-1}$$

To prove they are isomorphic we think a little:

$B = g'(b)$ is already diagonalised and so we have $B = \sigma(b)$
we could ask how we get

$$X B_1 X^{-1} = B$$

$$\text{or } B_1 = X^{-1} B X$$

and we must answer that the two columns of X must
be e-vectors for B with e-value -1 and 1 respectively.
A quick calculation finds that the -1 e-vector for
 B is $\begin{pmatrix} \alpha \\ -\alpha \end{pmatrix}$, 1 e-vector is $\begin{pmatrix} \beta \\ \beta \end{pmatrix}$.

So we'll let $X = \begin{pmatrix} \alpha & \beta \\ -\alpha & \beta \end{pmatrix}$ and then we'll get $X B_1 X^{-1} = B$

We have to determine α, β so that $X g'(a) X^{-1} = \sigma(a)$.

Rewriting this gives $X g'(a) = \cancel{\sigma(a)} X$ and so we need
to find α, β s.t.

~~$$\text{RHS} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ -\alpha \end{pmatrix} = \text{LHS}$$~~

$$X g'(a) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \sigma(a) X \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad X g'(a) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \sigma(a) X \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\text{i.e. } \begin{pmatrix} -\frac{1}{2}\alpha + \frac{\sqrt{3}}{2}\beta \\ \frac{1}{2}\alpha + \frac{\sqrt{3}}{2}\beta \end{pmatrix} = \begin{pmatrix} \alpha \\ 2\alpha \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} -\frac{\sqrt{3}}{2}\alpha - \frac{1}{2}\beta \\ \frac{\sqrt{3}}{2}\alpha - \frac{1}{2}\beta \end{pmatrix} = \begin{pmatrix} -\beta \\ 0 \end{pmatrix}$$

It's easy to check that $\sqrt{3}\alpha = \beta$ solves these eqn.
Therefore $\begin{pmatrix} 1 & \sqrt{3} \\ -1 & \sqrt{3} \end{pmatrix}$

$$\mathbb{C}^2 \xrightarrow{\quad} \mathbb{C}^2$$

gives an isomorphism between (g', \mathbb{C}^2) and (σ, \mathbb{C}^2)

$$(13) D_4 = \langle a, b : a^4 = b^2 = e, bab^{-1} = a^{-1} \rangle$$

Any 1-D repn' (over \mathbb{C}) must ~~not~~ be a group homom.

$$\rho : D_4 \longrightarrow \del{\mathbb{C}^*} \text{GL}(1, \mathbb{C}) = \mathbb{C}^*$$

and so it is determined by 2 non-zero complex nos $\rho(a), \rho(b)$. These cannot be arbitrary because they must satisfy the relations

$$\rho(a)^4 = 1$$

$$\rho(b)^2 = 1$$

$$\rho(b)\rho(a)\rho(b)^{-1} = \rho(a)^{-1}$$

These three cond's force $\rho(a) = \pm 1, \rho(b) = \pm 1$ as the four different possibilities. (In fact there are four 1-D repns as long as we are not in a field of characteristic 2, when there is only 1.)

$$(14) S_3 = \langle a, b : a^2 = b^2 = e, aba = bab \rangle$$

~~Let~~ let $\rho(a) := A = \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix}, \rho(b) := B = \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix}$. We must check that $A^2 = B^2 = \text{Id}_2, ABA = BAB$. This is an easy calculation.

(N.B. This shows that e, a, b, ab, ba, aba are distinct elements since ~~Now we said~~ all the matrices are distinct. This finishes off Q. 9(a) completely.).

In Q(b) we pointed out that $a \leftrightarrow (12) \quad b \leftrightarrow (23)$. Now look at the matrices for W given for (12), (23) in 3.6. They are exactly the above matrices!

Now suppose for a contradiction that this representation is reducible. Since this has degree 2 we must be able to

Find a subspace of $\dim^n 1$ stable under the S_3 action.
 Suppose Cv is such a subspace. Then we must
 have $g(a)(v) = \lambda v$ and $g(b)(v) = \mu v$ i.e. v is an e-vector
 for both ~~A~~ A and B . We'll calculate the e-vectors
 now:

$A = \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix}$ has e-values ± 1 ; e-vectors $\alpha \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ has value 1

e-vectors $\beta \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ has value 1

$B = \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix}$ has e-values ± 1 ; e-vectors $\gamma \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ value -1

e-vectors $\delta \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ value 1

All of these e-vectors are different, so the only possibility
 for v is 0 i.e. there is no 1-D stable subspace
 i.e. W is irreducible. \square