Step 11. Since $L=A R$, show that (5) implies $R G R^{t}=A G A=G$. Equating components in $R G=G R$, noting that $R R^{t}=I$, show that

$$
R=\left[\begin{array}{rr} 
\pm 1 & 0 \\
0 & S
\end{array}\right]
$$

where $S$ is $3 \times 3$ orthogonal in the standard basis. Hence $R$ has the same form in the basis $e_{0}, n, v_{3}, v_{4}$. This concludes the proof outline.

The physical interpretation of the theorem is worth noting: The theorem claims that if $L$ is linear and satisfies (2) and if $R$ is orientation preserving in the sense that $R_{11}=+1$ and $\operatorname{det} S=+1$, then $L$ is the transformation of coordinates from a rocket to a lab frame in which case $n$ points in the direction of motion of the rocket. Finally note that $L$ may be decomposed as $L=\tilde{R} \tilde{A}$. The reader will find that the relationships among $R, A, \tilde{R}, \tilde{A}$ have interesting computational details.

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# THE JORDAN CURVE THEOREM VIA THE BROUWER FIXED POINT THEOREM 

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A homeomorphic image of a closed interval $[a, b](a<b)$ is called an arc and a homeomorphic image of a circle is called a Jordan curve. One of the most classical theorems in topology is

Theorem (Jordan Curve Theorem). The complement in the plane $R^{2}$ of a Jordan curve $J$ consists of two components, each of which has $J$ as its boundary.

Since the first rigorous proof given by Veblen [4] in 1905, a variety of elementary (and lengthy) proofs have been provided by many authors. Among them, the one given by Moise [3] is intuitive and transparent yet lengthy. The purpose of this note is to provide a short proof by modifying Moise's method. In order to avoid the tedious arguments, we will use the following celebrated theorem of Brouwer (for an elementary proof, for example, see [1]).

Theorem (Brouwer Fixed Point Theorem). Every continuous map from a disk into itself has a fixed point.

To begin with, we note two simple facts concerning the components of $R^{2}-J$, where $J$ is a Jordan curve: (a) $R^{2}-J$ has exactly one unbounded component, and (b) each component of $R^{2}-J$ is path connected and open. The assertion (a) follows from the boundedness of $J$, and (b) from the local path-connectedness of $R^{2}$ and the closedness of $J$.

Lemma 1. If $R^{2}-J$ is not connected, then each component has $J$ as its boundary.
Proof. By assumption, $R^{2}-J$ has at least two components. Let $U$ be an arbitrary component. Since any other component $W$ is disjoint from $U$ and open, $W$ contains no point of the closure $\bar{U}$ and hence no point of the boundary $\bar{U} \cap U^{c}$ of $U$. Thus $\bar{U} \cap U^{c} \subset J$. Suppose $\bar{U} \cap U^{c} \neq J$. Then there exists an arc $A \subset J$ such that

$$
\bar{U} \cap U^{c} \subset A
$$

We will show that this leads to a contradiction. By the preceding remark (a), $R^{2}-J$ has at least one bounded component. Let $o$ be a point in a bounded component; if $U$ itself is bounded we choose $o$ in $U$. Let $D$ be a large disk with center $o$ such that its interior contains $J$. Then the boundary $S$ of $D$ is contained in the unbounded component of $R^{2}-J$. Since arc $A$ is homeomorphic to the interval $[0,1]$, the identity map $A \rightarrow A$ has a continuous extension $r: D \rightarrow A$ by the Tietze Extension Theorem (see, for example, [2]). We define a map $q: D \rightarrow D-$ $\{o\}$, according as $U$ is bounded or not, by

$$
q(z)=\left\{\begin{array}{ll}
r(z) & \text { for } z \in \bar{U}, \\
z & \text { for } z \in U^{c},
\end{array} \quad \text { or } q(z)= \begin{cases}z, & \text { for } z \in \bar{U} \\
r(z) & \text { for } z \in U^{c}\end{cases}\right.
$$

respectively. By (\#), the intersection of the two closed sets $\bar{U}$ and $U^{c}$ lies in $A$ on which $r$ is the identity map. Thus $q$ is well defined and continuous. Note that $q(z)=z$ if $z \in S$. Let $p: D-\{o\} \rightarrow S$ be the natural projection and let $t: S \rightarrow S$ be the antipodal map. Then the composition $t \cdot p \cdot q: D \rightarrow S \subset D$ has no fixed point. This contradicts the Brouwer fixed point theorem.

Note that the preceding proof implicitly contains a proof that no arc separates $R^{2}$, which is often a lemma to the Jordan curve theorem.

We need another lemma for our purpose. Let $E(a, b ; c, d)$ denote the rectangular set $\{(x, y) \mid a \leqslant x \leqslant b, c \leqslant y \leqslant d\}$ in the plane $R^{2}$, where $a<b$ and $c<d$.

Lemma 2. Let $h(t)=\left(h_{1}(t), h_{2}(t)\right)$ and $v(t)=\left(v_{1}(t), v_{2}(t)\right)(-1 \leqslant t \leqslant 1)$ be continuous paths in $E(a, b ; c, d)$ satisfying
(\#\#)

$$
h_{1}(-1)=a, \quad h_{1}(1)=b, \quad v_{2}(-1)=c, \quad v_{2}(1)=d .
$$

Then the two paths meet, i.e., $h(s)=v(t)$ for some $s, t$ in $[-1,1]$.
Proof. Suppose $h(s) \neq v(t)$ for all $s, t$. Let $N(s, t)$ denote the maximum-norm of $h(s)-v(t)$, i.e.,

$$
N(s, t)=\operatorname{Max}\left\{\left|h_{1}(s)-v_{1}(t)\right|, \quad\left|h_{2}(s)-v_{2}(t)\right|\right\} .
$$

Then $N(s, t) \neq 0$ for all $s, t$. We define a continuous map $F$ from $E(-1,1 ;-1,1)$ into itself by

$$
F(s, t)=\left(\frac{v_{1}(t)-h_{1}(s)}{N(s, t)}, \frac{h_{2}(s)-v_{2}(t)}{N(s, t)}\right) .
$$

Note that the image of $F$ is in the boundary of $E(-1,1 ;-1,1)$. To see that $F$ has no fixed point, assume $F\left(s_{0}, t_{0}\right)=\left(s_{0}, t_{0}\right)$. By the above remark, we have $\left|s_{0}\right|=1$ or $\left|t_{0}\right|=1$. Suppose, for example, $s_{0}=-1$. Then by (\#\#), the first coordinate of $F\left(-1, t_{0}\right),\left(v_{1}\left(t_{0}\right)-\right.$ $\left.h_{1}(-1)\right) / N\left(-1, t_{0}\right)$, is nonnegative and hence cannot equal $s_{0}(=-1)$. Similarly, the other possibilities of $\left|s_{0}\right|=1$ or $\left|t_{0}\right|=1$ cannot occur. This contradicts the Brouwer fixed point theorem since $E(-1,1 ;-1,1)$ is homeomorphic to a disk.

We are now ready to prove the Jordan curve theorem. By Lemma 1, we need only show that $R^{2}-J$ has one and only one bounded component. The proof will consist of the following three steps: Establishing the notation and defining a point $z_{0}$ in $R^{2}-J$; proving that the component $U$ containing $z_{0}$ is bounded; and proving that there is no bounded component other than $U$.

Since $J$ is compact, there exist points $a, b$ in $J$ such that the distance $\|a-b\|$ is the largest. We may assume that $a=(-1,0)$ and $b=(1,0)$. Then the rectangular set $E(-1,1 ;-2,2)$ contains $J$, and its boundary $\Gamma$ meets $J$ at exactly two points $a$ and $b$. Let $n$ be the middle point of the top side of $E(-1,1 ;-2,2)$, and $s$ the middle point of the bottom side; i.e., $n=(0,2)$ and $s=(0,-2)$. The segment $n s$ meets $J$ by Lemma 2. Let $l$ be the $y$-maximal point (that means the point $(0, y)$ with maximal $y$ ) in $J \cap \overline{n s}$. Points $a$ and $b$ divide $J$ into two arcs; we denote the one containing $l$ by $J_{n}$ and the other by $J_{s}$. Let $m$ be the $y$-minimal point in $J_{n} \cap \overline{n s}$ (possibly, $l=m$ ). Then the segment $\overline{m s}$ meets $J_{s}$; otherwise, the path $\overline{n l}+\widehat{l m}+\overline{m s}$ (where $\overparen{l m}$ denotes the subarc of $J_{n}$ with end points $l$ and $m$ ) could not meet $J_{s}$, contradicting Lemma 2. Let $p$ and $q$
denote the $y$-maximal point and the $y$-minimal point in $J_{s} \cap \overline{m s}$, respectively. Finally, let $z_{0}$ be the middle point of the segment $\overline{m p}$. (see Fig. 1).


FIG. 1
Now we show that $U$, the component of $R^{2}-J$ which contains $z_{0}$, is bounded. Suppose that $U$ is unbounded. Since $U$ is path connected, there exists a path $\alpha$ in $U$ from $z_{0}$ to a point outside $E(-1,1 ;-2,2)$. Let $w$ be the first point at which $\alpha$ meets the boundary $\Gamma$ of $E(-1,1 ;-2,2)$. Denote by $\alpha_{w}$ the part of $\alpha$ from $z_{0}$ to $w$. If $w$ is on the lower half of $\Gamma$, we can find a path $w s$ in $\Gamma$ from $w$ to $s$ which contains neither $a$ nor $b$. Now consider the path $\overline{n l}+\widehat{l m}+\overline{m z}_{0}+\alpha_{w}+\widehat{w s}$. This path does not meet $J_{s}$, contradicting Lemma 2. Similarly, if $w$ is on the upper half of $\Gamma$, the path $\overline{s z}_{0}+\alpha_{w}+\overline{w n}$ fails to meet $J_{n}$, where $\widehat{w n}$ is the shortest path in $\Gamma$ from $w$ to $n$. The contradiction shows that $U$ is a bounded component.

Finally suppose that there exists another bounded component $W(\neq U)$ of $R^{2}-J$. Clearly $W \subset E(-1,1 ;-2,2)$. We denote by $\beta$ the path $\overline{n l}+\widehat{I m}+\overline{m p}+\widehat{p q}+\overline{q s}$, where $\widehat{p q}$ is the subarc of $J_{s}$ from $p$ to $q$. As seen easily, $\beta$ has no point of $W$. Since $a$ and $b$ are not on $\beta$, there are circular neighborhoods $V_{a}, V_{b}$ of $a, b$, respectively, such that each of them contains no point of $\beta$. By Lemma 1, $a$ and $b$ are in the closure $\bar{W}$. Hence, there exist $a_{1} \in W \cap V_{a}$ and $b_{1} \in W \cap V_{b}$. Let $\widetilde{a_{1} b_{1}}$ be a path in $W$ from $a_{1}$ to $b_{1}$. Then the path $\overline{a a_{1}}+\widetilde{a_{1} b_{1}}+\overline{b_{1} b}$ fails to meet $\beta$. This contradicts Lemma 2 and completes our proof.

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