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Step 11. Since L = AR, show that (5) implies RGR' = AGA = G. Equating components in RG = GR, noting that RR' = I, show that

$$R = \begin{bmatrix} \pm 1 & 0 \\ 0 & S \end{bmatrix},$$

where S is 3×3 orthogonal in the standard basis. Hence R has the same form in the basis e_0, n, v_3, v_4 . This concludes the proof outline.

The physical interpretation of the theorem is worth noting: The theorem claims that if L is linear and satisfies (2) and if R is orientation preserving in the sense that $R_{11} = +1$ and det S = +1, then L is the transformation of coordinates from a rocket to a lab frame in which case n points in the direction of motion of the rocket. Finally note that L may be decomposed as $L = \tilde{R}\tilde{A}$. The reader will find that the relationships among $R, A, \tilde{R}, \tilde{A}$ have interesting computational details.

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THE JORDAN CURVE THEOREM VIA THE BROUWER FIXED POINT THEOREM

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A homeomorphic image of a closed interval [a, b] (a < b) is called an arc and a homeomorphic image of a circle is called a Jordan curve. One of the most classical theorems in topology is

THEOREM (Jordan Curve Theorem). The complement in the plane R^2 of a Jordan curve J consists of two components, each of which has J as its boundary.

Since the first rigorous proof given by Veblen [4] in 1905, a variety of elementary (and lengthy) proofs have been provided by many authors. Among them, the one given by Moise [3] is intuitive and transparent yet lengthy. The purpose of this note is to provide a short proof by modifying Moise's method. In order to avoid the tedious arguments, we will use the following celebrated theorem of Brouwer (for an elementary proof, for example, see [1]).

THEOREM (Brouwer Fixed Point Theorem). Every continuous map from a disk into itself has a fixed point.

To begin with, we note two simple facts concerning the components of $R^2 - J$, where J is a Jordan curve: (a) $R^2 - J$ has exactly one unbounded component, and (b) each component of $R^2 - J$ is path connected and open. The assertion (a) follows from the boundedness of J, and (b) from the local path-connectedness of R^2 and the closedness of J.

LEMMA 1. If $R^2 - J$ is not connected, then each component has J as its boundary.

Proof. By assumption, $R^2 - J$ has at least two components. Let U be an arbitrary component. Since any other component W is disjoint from U and open, W contains no point of the closure \overline{U} and hence no point of the boundary $\overline{U} \cap U^c$ of U. Thus $\overline{U} \cap U^c \subset J$. Suppose $\overline{U} \cap U^c \neq J$. Then there exists an arc $A \subset J$ such that

$$(\#) \qquad \qquad \overline{U} \cap U^c \subset A.$$

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We will show that this leads to a contradiction. By the preceding remark (a), $R^2 - J$ has at least one bounded component. Let o be a point in a bounded component; if U itself is bounded we choose o in U. Let D be a large disk with center o such that its interior contains J. Then the boundary S of D is contained in the unbounded component of $R^2 - J$. Since arc A is homeomorphic to the interval [0, 1], the identity map $A \rightarrow A$ has a continuous extension $r: D \rightarrow A$ by the Tietze Extension Theorem (see, for example, [2]). We define a map $q: D \rightarrow D - \{o\}$, according as U is bounded or not, by

$$q(z) = \begin{cases} r(z) & \text{for } z \in \overline{U}, \\ z & \text{for } z \in U^c, \end{cases} \text{ or } q(z) = \begin{cases} z & \text{for } z \in \overline{U}, \\ r(z) & \text{for } z \in U^c, \end{cases}$$

respectively. By (#), the intersection of the two closed sets \overline{U} and U^c lies in A on which r is the identity map. Thus q is well defined and continuous. Note that q(z) = z if $z \in S$. Let $p: D - \{o\} \rightarrow S$ be the natural projection and let $t: S \rightarrow S$ be the antipodal map. Then the composition $t \cdot p \cdot q: D \rightarrow S \subset D$ has no fixed point. This contradicts the Brouwer fixed point theorem.

Note that the preceding proof implicitly contains a proof that no arc separates R^2 , which is often a lemma to the Jordan curve theorem.

We need another lemma for our purpose. Let E(a, b; c, d) denote the rectangular set $\{(x, y) | a \le x \le b, c \le y \le d\}$ in the plane \mathbb{R}^2 , where a < b and c < d.

LEMMA 2. Let $h(t) = (h_1(t), h_2(t))$ and $v(t) = (v_1(t), v_2(t))$ $(-1 \le t \le 1)$ be continuous paths in E(a, b; c, d) satisfying

$$(\#\#)$$
 $h_1(-1) = a, h_1(1) = b, v_2(-1) = c, v_2(1) = d.$

Then the two paths meet, i.e., h(s) = v(t) for some s, t in [-1,1].

Proof. Suppose $h(s) \neq v(t)$ for all s, t. Let N(s, t) denote the maximum-norm of h(s) - v(t), i.e.,

$$N(s,t) = \max\{ |h_1(s) - v_1(t)|, |h_2(s) - v_2(t)| \}.$$

Then $N(s, t) \neq 0$ for all s, t. We define a continuous map F from E(-1, 1; -1, 1) into itself by

$$F(s,t) = \left(\frac{v_1(t) - h_1(s)}{N(s,t)}, \frac{h_2(s) - v_2(t)}{N(s,t)}\right).$$

Note that the image of F is in the boundary of E(-1,1; -1, 1). To see that F has no fixed point, assume $F(s_0, t_0) = (s_0, t_0)$. By the above remark, we have $|s_0| = 1$ or $|t_0| = 1$. Suppose, for example, $s_0 = -1$. Then by (# #), the first coordinate of $F(-1, t_0)$, $(v_1(t_0) - h_1(-1))/N(-1, t_0)$, is nonnegative and hence cannot equal $s_0(= -1)$. Similarly, the other possibilities of $|s_0| = 1$ or $|t_0| = 1$ cannot occur. This contradicts the Brouwer fixed point theorem since E(-1, 1; -1, 1) is homeomorphic to a disk.

We are now ready to prove the Jordan curve theorem. By Lemma 1, we need only show that $R^2 - J$ has one and only one bounded component. The proof will consist of the following three steps: Establishing the notation and defining a point z_0 in $R^2 - J$; proving that the component U containing z_0 is bounded; and proving that there is no bounded component other than U.

Since J is compact, there exist points a, b in J such that the distance ||a - b|| is the largest. We may assume that a = (-1, 0) and b = (1, 0). Then the rectangular set E(-1, 1; -2, 2) contains J, and its boundary Γ meets J at exactly two points a and b. Let n be the middle point of the top side of E(-1, 1; -2, 2), and s the middle point of the bottom side; i.e., n = (0, 2) and s = (0, -2). The segment \overline{ns} meets J by Lemma 2. Let l be the y-maximal point (that means the point (0, y) with maximal y) in $J \cap \overline{ns}$. Points a and b divide J into two arcs; we denote the one containing l by J_n and the other by J_s . Let m be the y-minimal point in $J_n \cap \overline{ns}$ (possibly, l = m). Then the segment \overline{ms} meets J_s ; otherwise, the path $\overline{nl} + \overline{lm} + \overline{ms}$ (where \overline{lm} denotes the subarc of J_n with end points l and m) could not meet J_s , contradicting Lemma 2. Let p and q

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denote the y-maximal point and the y-minimal point in $J_s \cap \overline{ms}$, respectively. Finally, let z_0 be the middle point of the segment \overline{mp} . (see Fig. 1).





Now we show that U, the component of $R^2 - J$ which contains z_0 , is bounded. Suppose that U is unbounded. Since U is path connected, there exists a path α in U from z_0 to a point outside E(-1,1; -2, 2). Let w be the first point at which α meets the boundary Γ of E(-1,1; -2, 2). Denote by α_w the part of α from z_0 to w. If w is on the lower half of Γ , we can find a path \widehat{ws} in Γ from w to s which contains neither a nor b. Now consider the path $\overline{nl} + \overline{lm} + \overline{mz_0} + \alpha_w + \widehat{ws}$. This path does not meet J_s , contradicting Lemma 2. Similarly, if w is on the upper half of Γ , the path $\overline{sz_0} + \alpha_w + \widehat{wn}$ fails to meet J_n , where \widehat{wn} is the shortest path in Γ from w to n. The contradiction shows that U is a bounded component.

Finally suppose that there exists another bounded component $W(\neq U)$ of $R^2 - J$. Clearly $W \subset E(-1,1; -2,2)$. We denote by β the path $\overline{nl} + \widehat{lm} + \overline{mp} + \widehat{pq} + \overline{qs}$, where \widehat{pq} is the subarc of J_s from p to q. As seen easily, β has no point of W. Since a and b are not on β , there are circular neighborhoods V_a, V_b of a, b, respectively, such that each of them contains no point of β . By Lemma 1, a and b are in the closure \overline{W} . Hence, there exist $a_1 \in W \cap V_a$ and $b_1 \in W \cap V_b$. Let $\widehat{a_1b_1}$ be a path in W from a_1 to b_1 . Then the path $\overline{aa_1} + \widehat{a_1b_1} + \overline{b_1b}$ fails to meet β . This contradicts Lemma 2 and completes our proof.

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