## Mond conjecture for mappings on ICIS

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Still open for $n \geq 3$.

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- $(X, 0)$ isolated complete intersection singularity (ICIS) of dimension $\geq 1$, then

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with equality iff $(X, 0)$ is weighted homogeneous. Non-trivial:

- w.h. implies $=$, Greuel (1980),
- $\geq$, Looijenga \& Steenbrik (1985),
- = implies w.h., Vosegaard (2002).
- Suppose $f:\left(\mathbb{C}^{n}, S\right) \rightarrow\left(\mathbb{C}^{p}, 0\right)$ has isolated instability and $(n, p)$ are nice dimensions, with $n \geq p$. Then,

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It was proved by Damon \& Mond (Invent. Math. 1991).

## Conjecture (Generalised Mond conjecture)

Suppose $f:(X, S) \rightarrow\left(\mathbb{C}^{n+1}, 0\right)$ has isolated instability where $(X, S)$ is an $n$-dimensional ICIS and $(n, n+1)$ are nice dimensions. Then,

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The Thom-Mather theory for mappings on ICIS $f:(X, S) \rightarrow\left(\mathbb{C}^{p}, 0\right)$ was developed by Mond \& Montaldi (1996).
In the same paper: if $n \geq p$ and ( $n, p$ ) are nice dimensions, then
$\operatorname{codim}_{\mathscr{A}_{e}}(X, f) \leq \mu_{\Delta}(X, f)$,
with equality if $(X, f)$ is weighted homogeneous (generalised Damon \& Mond theorem).

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Our proof is based on the construction of a generalised Jacobian module, which controls the image Milnor number.

## Reasons to consider the generalised Mond conjecture:

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- It is also a generalisation of the classical $\mu \geq \tau$-inequality for IHS. In fact, if $(X, 0)$ is an IHS and $i:(X, 0) \hookrightarrow\left(\mathbb{C}^{n+1}, 0\right)$ is the inclusion, then

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Take $H$ a generic hyperplane in $\mathbb{C}^{n+1}, 0 \in H$. Then $X=f^{-1}(H)$ is now an ICIS of dimension $n-1$ and consider $\left.f\right|_{X, S}:(X, S) \rightarrow H$. We have a Lê-Greuel type formula for $\mu_{I}(f)$.

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If $f$ has corank one, the double point space $D^{2}(f) \subset \mathbb{C}^{n} \times \mathbb{C}^{n}$ is an ICIS of dimension $n-1$ and consider the projection $\pi_{1}: D^{2}(f) \rightarrow \mathbb{C}^{n}$. Then $\mu_{I}\left(D^{2}(f), \pi_{1}\right)$ is strongly related to $\mu_{I}(f)$, Giménez-Conejero \& JJNB (Adv. Math. 2023).


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where the columns are biholomorphisms.
Unfoldings (deformations): we deform both the variety $X$ and the map $f$ simultaneously.

An unfolding is a pair $(\mathcal{X}, F)$, where $F:(\mathcal{X}, S) \rightarrow\left(\mathbb{C}^{p} \times \mathbb{C}^{r}, 0\right)$ is a map germ together with a flat projection $\pi:(\mathcal{X}, S) \rightarrow\left(\mathbb{C}^{r}, 0\right)$ such that the following diagram commutes

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For each parameter $u \in \mathbb{C}^{r}$, we have a mapping $f_{u}: X_{u} \rightarrow V_{u} \subseteq \mathbb{C}^{p}$, where $X_{u}=\pi^{-1}(u)$ and $f_{u}$ is the restriction of $\pi_{1} \circ F$. This is called a perturbation, denoted by $\left(X_{u}, f_{u}\right)$.

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We can see the unfolding $(\mathcal{X}, F)$ as a family $\left\{\left(X_{u}, f_{u}\right)\right\}_{u \in \mathbb{C}^{r}}$ which deforms $(X, f)$.
$\mathscr{A}$-equivalence of unfoldings: There exist $\Phi$ and $\Psi$ unfoldings of the identity on $(X, S)$ and $\left(\mathbb{C}^{p}, 0\right)$ resp, such that for each parameter $u \in \mathbb{C}^{r}$ we have $\mathscr{A}$-equivalence of mappings:

$$
\begin{aligned}
& X_{u} \xrightarrow{f_{u}} V_{u} \\
& \boldsymbol{L}_{u} \\
& X_{u}^{\prime} \xrightarrow{f_{u}^{\prime}} \xrightarrow{\psi_{u}} V_{u}^{\prime}
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A pair $(X, f)$ has isolated instability if there exits a representative $f: X \rightarrow V \subseteq \mathbb{C}^{p}$ such that $f$ has only stable singularities on $V \backslash\{0\}$.
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A stabilisation is a 1-parameter unfolding such that $\left(X_{t}, f_{t}\right)$ has only stable singularities, if $t \in \mathbb{C}, t \neq 0$ (stable perturbation).

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Any pair $(X, f)$ with isolated instability admits a stabilisation, provided that ( $n, p$ ) are nice dimensions in the sense of Mather or $f$ has only kernel rank one singularities

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Change of parameter space: Given $\varphi:\left(\mathbb{C}^{s}, 0\right) \rightarrow\left(\mathbb{C}^{r}, 0\right)$ we construct a new unfolding whose perturbation is $\left(X_{\varphi(v)}, f_{\varphi(v)}\right)$ for each $v \in \mathbb{C}^{s}$.

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An unfolding is versal if any other unfolding is obtained by change of parameter space and $\mathscr{A}$-equivalence.

The $\mathscr{A}_{e}$-codimension of $(X, f)$ is defined as

$$
\operatorname{codim}_{\mathscr{A}_{e}}(X, f)=\operatorname{dim}_{\mathbb{C}} \frac{\theta(f)}{t f\left(\theta_{X, S}\right)+\omega f\left(\theta_{p}\right)}+\sum_{x \in S} \tau(X, x)
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## Example

$(X, 0)$ is an ICIS in $\left(\mathbb{C}^{n+k}, 0\right)$, inclusion $i:(X, 0) \rightarrow\left(\mathbb{C}^{n+k}, 0\right)$. By construction, $\omega i\left(\theta_{n+k}\right)=\theta(i)$, hence

$$
\operatorname{codim}_{\mathscr{A}_{e}}(X, i)=\tau(X, 0)
$$

Theorem (Versality theorem, Mond \& Montaldi 1996)
$(X, f)$ admits a versal unfolding iff it is $\mathscr{A}$-finite. In such case, $\operatorname{codim}_{\mathscr{A}_{e}}(X, f)$ is the minimal number of parameters in a versal unfolding.

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## Theorem (Generalised Mather-Gaffney criterion)

$(X, f)$ has isolated instability iff it is $\mathscr{A}$-finite.

From now on, we consider only pairs $(X, f)$, where $f:(X, S) \rightarrow\left(\mathbb{C}^{n+1}, 0\right)$ is $\mathscr{A}$-finite and either $(n, n+1)$ are nice dimensions or $f$ has corank one.

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## Theorem (Mond, 1991 adapted by Giménez-Conejero \& JJNB, 2023)

Take a stable perturbation $\left(X_{t}, f_{t}\right)$. Then $f_{t}\left(X_{t}\right) \cap B_{\epsilon}$ has the homotopy type of a bouquet of $n$-spheres, $\forall 0<\eta \ll \epsilon \ll 1$ and $0<|t|<\eta$. The number of such spheres $\beta_{n}\left(f_{t}\left(X_{t}\right) \cap B_{\epsilon}\right)$ is independent of the choice of $\eta, \epsilon, t$ and the stabilisation.

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Take a stable perturbation $\left(X_{t}, f_{t}\right)$. Then $f_{t}\left(X_{t}\right) \cap B_{\epsilon}$ has the homotopy type of a bouquet of $n$-spheres, $\forall 0<\eta \ll \epsilon \ll 1$ and $0<|t|<\eta$. The number of such spheres $\beta_{n}\left(f_{t}\left(X_{t}\right) \cap B_{\epsilon}\right)$ is independent of the choice of $\eta, \epsilon, t$ and the stabilisation.
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## Example

Let $(X, 0)$ be an IHS and consider the inclusion $i:(X, 0) \rightarrow\left(\mathbb{C}^{n+1}, 0\right)$. We take a reduced equation $g \in \mathscr{O}_{n+1}$. For each $t \neq 0, X_{t}=g^{-1}(t)$ is smooth and $i: X_{t} \rightarrow \mathbb{C}^{n+1}$ the inclusion is stable. We have

$$
\mu_{l}(X, i)=\beta_{n}\left(X_{t} \cap B_{\epsilon}\right)=\mu(X, 0) .
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## The generalised Jacobian module

The Jacobian module was introduced in a paper by Bobadilla, JJNB \& Peñafort (2019) for map germs $f:\left(\mathbb{C}^{n}, S\right) \rightarrow\left(\mathbb{C}^{n+1}, 0\right)$. Here we present a generalised version for mappings on ICIS.

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We choose $h:\left(\mathbb{C}^{n+k}, S\right) \rightarrow\left(\mathbb{C}^{k}, 0\right)$ reduced equation of $(X, S)$ and $\tilde{f}:\left(\mathbb{C}^{n+k}, S\right) \rightarrow\left(\mathbb{C}^{p}, 0\right)$ an analytic extension of $f$. We define

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Then $\left(\mathbb{C}^{n+k}, \hat{f}\right)$ is an unfolding of $(X, f)$ with smooth base $\mathbb{C}^{n+k}$ and with parameter space $\mathbb{C}^{k}$.
If $(X, 0)$ has embedding dimension $n+k$, then $\left(\mathbb{C}^{n+k}, \hat{f}\right)$ is a minimal unfolding with smooth base.

Since $f$ is finite, $\hat{f}$ is also finite and its image is a hypersurface in ( $\mathbb{C}^{n+1} \times \mathbb{C}^{k}, 0$ ). Let $\hat{g} \in \mathscr{O}_{n+1+k}$ be a reduced equation of its image.

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We also put $g \in \mathscr{O}_{n+1}, g(y)=\hat{g}(y, 0)$, which is a reduced equation of the image of $f$.

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The generalised Jacobian module is

$$
M(g)=\frac{\left(\hat{f}^{*}\right)^{-1}\left(J(\hat{\mathrm{~g}}) \cdot \mathscr{O}_{n+k}\right)}{J_{y}(\hat{\mathrm{~g}})} \otimes \frac{\mathscr{O}_{k}}{\mathfrak{m}_{k}},
$$

where $J_{y}(\hat{g})=$ the relative Jacobian ideal, generated in $\mathscr{O}_{n+1+k}$ by $\partial \hat{g} / \partial y_{i}, i=1, \ldots, n+1$.

## Example

Let $(X, 0)$ be an IHS and consider the inclusion $i:(X, 0) \rightarrow\left(\mathbb{C}^{n+1}, 0\right)$. We have $\hat{g}(y, t)=g(y)-t$, where $g \in \mathscr{O}_{n+1}$ is the equation of $(X, 0)$. Thus, $J(\hat{g})=\mathscr{O}_{n+2}$ and

$$
M(g)=\frac{\mathscr{O}_{n+2}}{J_{y}(\hat{g})} \otimes \frac{\mathscr{O}_{1}}{\mathfrak{m}_{1}} \cong \frac{\mathscr{O}_{n+1}}{J(g)},
$$

the Jacobian algebra.

## Theorem

Suppose $(X, f)$ has isolated instability and $(n, n+1)$ nice dimensions, $n \geq 2$, then

$$
\operatorname{dim}_{\mathbb{C}} M(g)=\operatorname{codim}_{\mathscr{A}_{e}}(X, f)+\operatorname{dim}_{\mathbb{C}} \frac{J(g)+(g)}{J(g)}
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Corollary

$$
\operatorname{dim}_{\mathbb{C}} M(g) \geq \operatorname{codim}_{\mathscr{A}_{e}}(X, f),
$$

with equality if $(X, f)$ is w.h.

Now we consider only unfoldings with smooth base, so we can assume they are also unfoldings of the minimal unfolding with smooth base $\left(\mathbb{C}^{n+k}, \hat{f}\right)$.

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with $F(x, z)=\left(f_{z}(x), h(x), z\right)$ such that $h^{-1}(0)=X$ and $f_{0} \mid x=f$.

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Again, the image of $F$ is a hypersurface in $\left(\mathbb{C}^{n+1} \times \mathbb{C}^{k} \times \mathbb{C}^{r}, 0\right)$. We take $G \in \mathscr{O}_{n+1+k+r}$ a reduced equation.

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The relative generalised Jacobian module is

$$
M_{r e l}(G)=\frac{\left(F^{*}\right)^{-1}\left(J_{y, z}(G) \cdot \mathscr{O}_{n+k+r}\right)}{J_{y}(G)}
$$

## Theorem

We have an exact sequence:

$$
0 \longrightarrow M_{r e l}(G) \longrightarrow \frac{F_{1}(F)}{J_{y}(G)} \longrightarrow \frac{C(F)}{J_{y, z}(G) \cdot \mathscr{O}_{n+k+r}} \longrightarrow 0 .
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$F_{1}(F):=$ first Fitting ideal of $\mathscr{O}_{n+k+r}$ as $\mathscr{O}_{n+1+k+r}$-module via $F^{*}: \mathscr{O}_{n+1+k+r} \rightarrow \mathscr{O}_{n+k+r}$ and $C(F):=F_{1}(F) \cdot \mathscr{O}_{n+k+r}$.

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## Lemma (Piene (1979), Bruce \& Marar (1996))

$$
\frac{C(F)}{J_{y, z}(G) \cdot \mathscr{O}_{n+k+r}} \cong \frac{\mathscr{O}_{n+k+r}}{R(F)},
$$

where $R(F)$ is the ramification ideal, generated by the maximal minors of the Jacobian matrix of $F$. In particular, it is Cohen-Macaulay of dimension $n+k+r-2$.

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## Theorem

Let $F$ be any unfolding such that $\mathscr{B}(F) \subsetneq\left(\mathbb{C}^{k+r}, 0\right)$. Then,

$$
\mu_{l}(X, f)=e\left(\mathfrak{m}_{k+r} ; M_{r e l}(G)\right),
$$

the Samuel multiplicity of $M_{r e l}(G)$ as $\mathscr{O}_{k+r}$-module via the projection onto the parameter space.

## Corollary

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\mu_{I}(X, f) \leq \operatorname{dim}_{\mathbb{C}} M(g),
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If we want to prove the Mond conjecture by means of the Jacobian module, we have to show that $\mu_{l}(X, f)=\operatorname{dim}_{\mathbb{C}} M(g)$.

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Conjecture (Strong generalised Mond conjecture)

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## Proof for $n=2$

Theorem (Strong generalised Mond conjecture for $n=2$ )
Let $f:(X, S) \rightarrow\left(\mathbb{C}^{3}, 0\right)$ be with isolated instability, $(X, S)$ a 2-dimensional ICIS. Then

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We have $\operatorname{dim}_{\mathbb{C}} M(g)<\infty$ and $M(g) \cong M_{r e l}(G) \otimes \mathscr{O}_{k+r} / \mathfrak{m}_{k+r}$. This implies $\operatorname{dim} M_{r e l}(G) \leq k+r$.

Recall that we have an exact sequence

$$
0 \longrightarrow M_{r e l}(G) \longrightarrow \frac{F_{1}(F)}{J_{y}(G)} \longrightarrow \frac{C(F)}{J_{y, z}(G) \cdot \mathscr{O}_{2+k+r}} \longrightarrow 0
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By a lemma of Pellikaan (1988), the three conditions above imply that $F_{1}(F) / J_{y}(G)$ is also Cohen-Macaulay.

Finally, we use the depth lemma:

$$
\text { depth } \begin{aligned}
M_{r e l}(G) & \geq \min \left\{\operatorname{depth}\left(\frac{F_{1}(F)}{J_{y}(G)}\right), \operatorname{depth}\left(\frac{C(F)}{J_{y, z}(G) \cdot \mathscr{O}_{n+r}}\right)+1\right\} \\
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On the other hand,

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therefore

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$$

so $M_{\text {rel }}(G)$ is Cohen-Macaulay.

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That is, the stable perturbation is $\left(X_{t}, f_{t}\right)$, where $f_{t}(x, y, z)=\left(x, y, z^{3}+x z+y^{2}\right)$ and $X_{t}=\left\{x^{3}+y^{3}-z^{2}=t\right\}$.

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With Singular, one easily obtains that $\operatorname{codim}_{\mathscr{A}_{e}}(X, f)=6$ and $\mu_{I}(X, f)=\operatorname{dim}_{\mathbb{C}} M(g)=6$.

